**Extensions of the Einstein field equations and their solutions**

Mikhail Batanov[[1]](#footnote-1), Ph.D., Associate Professor,

Department 207, Moscow Aviation Institute,

Moscow, Russia

**Abstract**

One of the aims of geometrophysics[[2]](#footnote-2) is to eliminate the concept of mass as a fundamental property. We present here a promising approach to achieving this end. In order to do this, we consider the interface between different solutions of the Einstein field equations, and construct an extension of these equations and their solutions. This forms the basis of a metric-dynamic model of particles of varying sizes, including virtually all elementary particles that are part of the Standard Model.

**Keywords**: vacuum, Einstein field equation, the Ricci-flat space, the signature of a metric of the vacuum, the Standard Model.

**A note on terminology**: *New concepts are introduced using either terms coined by the author, or new usages of words already in use for similar concepts. At appropriate places in the text, we call the attention of the reader to the new terminology with explanations preceded by the word “terminology” in bold. These terms are tentative, and**the author welcomes suggestions for improvements on the terminology.*

**1. The first Einstein field equation and its solutions**

1(a) Consider the Einstein field equations

 (1.1)

where *gij* are metric tensor components;

 is the Ricci tensor; (1.2)

*R* = *gikRik*  represents scalar curvature; (1.3)

 are Christoffel symbols. (1.4)

The solutions to (1.1) are considered in many works on modern differential geometry and general relativity. However, no work is known to the author which discusses the relationship between the different solutions of these equations in detail. We propose to fill this gap.

Combining (1.1) with *gik*, we obtain (Novikov and Taimanov 2014)

 (1.5)

because  of the number of spatial dimensions.

For any *n*-dimensional space (except for *n* = 2), Equation (1.5) can only be performed when *R* = 0. Therefore, for *n* = 4, Equation (1.1) becomes

. (1.6)

The solutions to (1.6) are best expressed, as a rule, in a spherical coordinate system in the form of metrics. Before we present these metrics, we need to insert a note about our terminology.

1(b) **Terminology:** *The term "signature” used here is an extension of the usual means to determine where a metric component is positive definite or negative definite. More broadly, suppose a space S of points* *s*=(*x*0,*x*1,*x*2,*x*3) *has several metrics or pseudometrics defined on it, such that each metric or pseudometric* [*ds*]*i* *is described by* [*ds*]*i*2= *a*0 *f*1*(s,p)dx*02*+ a*1 *f*2*(s,p)dx*12 *+* *a*2 *f*3*(s,p)dx*22 *+ a*3 *f*3 *(s,p)dx*32, *where for* *i* ∈{0,1,2,3}, *fi*(*s*) *are positive definite functions defined on S, p are given parameters, and* *ai* ∈{0,1,1}. (*For convenience, we shall drop “or pseudometric” and the mention of the parameters in the rest of this section*.) *Then, if this is a quadratic (metric) form, we form the ordered tuple* (*a*0, *a*1, *a*2, *a*3), *whereby  is abbreviated “” and 1 is abbreviated “+” (0 retains its name). We then term it a “signature” of the metric. If, on the other hand, the defining equation of each of the metrics is a linear (affine) form or "colored" quaternion (“colored” to be explained later), we term it a “stignature” to emphasize this difference. However, in what follows, the rules for signatures extend in a natural way to stignatures.*

*Suppose further that several metrics are defined on the region in question such that they only differ in the sign of their coefficients. This would allow a set of 64 possible metrics in such a set.*

*Now we use the fact that the sum of two metrics yields another metric. To complement this situation, we can define an operation, a component-wise addition: if there are two signatures in the set* (*a*0, *a*1, *a*2, *a*3) *and* (*b*0, *b*1, *b*2, *b*3), *then* (*a*0, *a*1, *a*2, *a*3) (*b*0, *b*1, *b*2, *b*3) = (*a*0+*b*0, *a*1+*b*1, *a*2+*b*2, *a*3+*b*3) *if and only if* (*a*0+*b*0, *a*1+*b*1, *a*2+*b*2, *a*3+*b*3); *that is, the sum of the signatures of metrics is the signature of the sum of the corresponding metrics. Such a set of 64 signatures will form a group under .We henceforth drop the tilde, using + for both normal addition and this operation, where the difference will be clear from the context.*

*We can also form various substructures. For example, the aforementioned difference between a signature and a stignature is one distinction. Restrictions of the fact that the metrics are defined on spacetime introduces further restrictions. Furthering such considerations, the functions we will be using will fulfill the condition that* *a*0×*a*1×*a*2×*a*3 = 0 *if and only if* *a*0=*a*1=*a*2=*a*3= 0. *(The reason for this will become apparent later in the paper. Since the resulting substructure of only 17 elements no longer forms a group under the same operation as before, lacking closure, further restrictions on the operation needs to be made to enjoy the consequences of the group structure.) Other restrictions will limit the number of elements even further, or require further structure. Taking all of these possibilities together into a single structure is beyond the scope of this paper, but this algebra, which we term the “Algebra of signatures”, is more fully outlined in an article by Gaukhman (Gaukhman 2007), and applied in numerous subsequent papers by the same author as listed in the bibliography. These are presently only available in Russian, but the author intends to bring this to a wider audience over a series of future articles in English in the near future.*

*In this paper, most of the metrics will be expressed so that the spatial portion is expressed in spherical coordinates (r, θ, ϕ), so that x0 ≡ t, x1 ≡ r, x2≡ θ, x3 ≡ ϕ, and the metric is expressed as:*

*ds*(–)2 = *a*1 *f1(t)dt*2*+ a*2 *f*2*(r)dr*2 *+* *a*3 *f3 (r)dθ* 2 *+ a*4*f*4 *(r,θ)dϕ* 2.

*For this reason, we shall refer to the regions of vacuum on which the metrics are defined as “spherical formations”. The fact that measurements of most particles are spherically symmetrical is a further support for the intuitive feel of this term.*

**1(c)** We return to

*ds*(–)2 = *еνс*2*dt*2*– еλdr*2 *– r*2*dθ* 2 * r*2sin2*θ dϕ* 2 with the signature (+** **), (1.7)

*ds*(+)2 = *–еνс*2*dt*2*+ еλdr*2 *+ r*2*dθ* 2 *+ r*2sin2*θ dϕ* 2 with the signature(– + + +), (1.8)

where ** and ** are the sought-after functions of *t* and *r* respectively.

As a result of the substitution of covariant and contravariant components of the metric tensor of the metric (1.7) in equation (1.6) for fixed (i.e., time-independent) vacuum states, we obtain a system of three equations (Landau and Lifshitz 1988):

*ν = – λ*; (1.9)

–*е ν*(*ν′ /r* + 1/*r*2) + 1/*r*2 = 0; (1.10)

*ν′′* + *ν′* 2 + 2*ν′ /r* = 0. (1.11)

The differential equation (1.10) has three solutions:

*ν*1 = ln(*h*1+ *h*2 /*r*), *ν*2 = ln(*h*1 – *h*2 /*r*), *ν*3 = *h*3, (1.12)

where *h*1, *h*2, *h*3 are integration constants.

Equation (1.11) also has three solutions:

*ν* 1 = ln(1+ *b/r*), *ν* 2 = ln(1 – *b/r*), *ν* 3 = 0, (1.13)

where *b* is a constant of integration.

If *h*1 = 1, *h*2 = *b*, and *h*3 = 0, the solutions to (1.12) and to (1.13) coincide.

Substituting the three possible solutions (1.13) in the metric (1.7) with (1.9) we obtain the three metrics with the same signature (+   ):

*dsa*(–)2 = (1– *r*0*/r*)*с*2*dt*2 – (1– *r*0*/r*) –1*dr*2 – *r*2*dθ* 2 – *r*2sin2*θ* *dϕ* 2, (1.14)

*dsb*(–)2 = (1+ *r*0*/r*)*с*2*dt*2 – (1+ *r*0*/r*) –1*dr*2 – *r*2*dθ* 2 – *r*2sin2*θ dϕ* 2, (1.15)

*ds*c(–)2 = *с*2*dt*2 – *dr*2 – *r*2*dθ* 2 – *r*2sin2*θ* *dϕ* 2. (1.16)

where *r*0 = *b* is the radius of the corresponding closed sphere.

By doing the same operations with the components of the metric tensor of the metric (1.8), we obtain the following three metrics, also satisfying Equation (1.6), but with opposite signature ( + + +):

*dsa*(+)2 = – (1– *r*0*/r*)*с*2*dt*2 + (1– *r*0*/r*) –1*dr*2 + *r*2*dθ* 2 + *r2*sin2*θ* *dϕ* 2, (1.17)

*dsb*(+)2 = – (1+ *r*0*/r*)*с*2*dt*2 + (1+ *r*0*/r*) –1*dr*2 + *r*2*dθ* 2 + *r2*sin2*θ dϕ* 2), (1.18)

*dsc*(+)2 = – *с*2*dt*2 + *dr*2 + *r*2*dθ* 2 + *r2*sin2*θ* *dϕ* 2). (1.19)

Each of the metrics (1.14) through (1.19) is irreducible to the others; together this is called a generalized Schwarzschild metric.

Metrics (1.14) through (1.19) describe the state of the same region of the vacuum. Therefore we consider different variants of their averages, in spite of the fact that equation (1.6) is non-linear; in general, in such cases the sum of the solutions is not itself a solution.

If the centers of the metrics (1.14) through (1.16) and (1.17) through (1.19) coincide, evidently they will sum to zero

*dsa*(–)2+*dsb*(–)2+*dsc*(–)2*+dsa*(+)2+*dsb*(+)2+*dsc*(+)2 = 0*∙с*2*dt*2*+*0*∙dr*2 *+* 0*∙* *dθ* 2*+* 0*∙*sin2*θ dϕ* 2= 0. (1.20)

The resulting metric is

*ds*(0)2 = *gij*(0)*dxi**dxj*, (1.21)

where  (1.22)

A vacuum state is a trivial solution of (1.6).

Thus, contrary to expectation, the addition of the six metrics (1.14) through (1.19) leads to the production of additional solutions of (1.6).

Let us now consider the arithmetic average of the two metrics (1.14) and (1.15)

 (1.23)

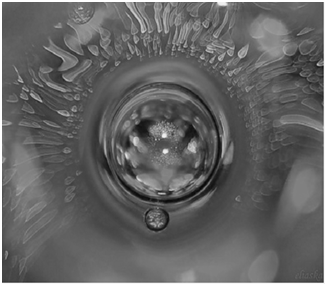
The distance between two points *r*1 and *r*2 in a region with signature (+ ) is determined by the following expression in General Relativity:

. (1.24)

By substituting *g*11() into the average of the metric (1.23), we obtain

. (1.25)

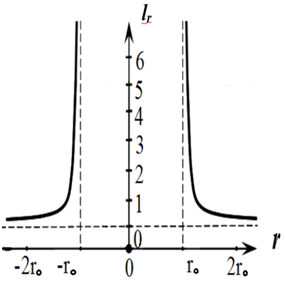
First we find the value of the interval between the points *r*1 *=* 0 and *r*2 = *r*0:



**Fig. 1.1** Air bubble in liquid

. (1.26)

The length of this segment is equal to the radius of the cavity *r*0, and the vacuity of this result suggests that there is no vacuum cavity. Outside the cavity and from *r*1 *= r*0 to *r*2 = ∞, we have



**Fig. 1.2** Graph of the function *lr*(–): relative length of the vacuum in the outer shell surrounding the spherical cavity. Executed in MathCad 14 for *r*0 = 2

. (1.27)

In the absence of deformation, the distance between points *r*2=∞ and *r*1 =*r*0 is equal to ∞ – *r*0, and in this case this is equal to (1.27). The difference between these segments is approximately equal to . (1.28)

This result shows that the average length of the vacuum on the interval ]*r*0, ∞[ is compressed by an amount ~ *r*0 in all radial directions due to the fact that it was forced out of the cavity radius (1.28). This result is similar to the air bubble in the liquid (Figure 1.1). The difference between the original uncurved local area vacuum state and its current (curved) status is determined by the difference expressed in (1.29). (Sedov 1994, Gaukhman 2004)

*ds*(–)2 – *ds*0(–)2 = (*gij*(–) – *gij*0(–)) *dxidxj*, (1.29)

where the *gii*0(–) make up the components of the metric tensor in the uncurved area of the vacuum.

The relative lengthening of the one of side of the vacuum region is expressed by

 (1.30)

which implies  *ds*(–)2 *=* (1+ *l*(–))2 *ds*0(–)2, (1.31)

and

 (1.32)

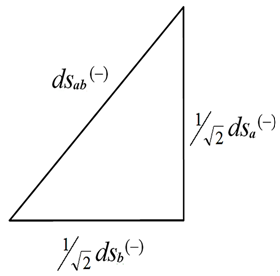
The uncurved state of the section under consideration in a vacuum state is given by the metric (1.16). Therefore, substituting components *gii*0(–) and *gii*(–), respectively, from (1.16) and (1.23) to (1.32), we obtain

, , , . (1.33)

The graph of the functions *lr*(–) is shown in Figure 1.2. At *r* = *r*0, the function tends to infinity, and when *r* < *r*0 it becomes the complex function. This once again confirms that, within the scope of [0, *r*0], there is a cavity, as in Figures 1.1 and 1.2.

Thus, averaging the metrics (1.14) and (1.15) leads to the metric-dynamic description of the stable formation of a vacuum-type "air bubble in a liquid", while the metrics (1.14) or (1.15) alone do not lead to such results.

**Fig. 1.3** Values of segments *dsa*(–)and *dsb* (–)



**Fig. 1.4.** A double helix can be projected onto a plane such that the tangents of the resulting curves are perpendicular to one another at the points of intersection.

We note the following important fact. The average quadratic form (1.23) *dsab*(–)2 =(*dsa* (–)2*+ dsb* (–)2) (1.34)

naturally evokes the Pythagorean theorem *a*2 + *b*2 = *c*2. This means that the line segments ()1/2*dsa*(–)and()1/2*dsb*(–) are always mutually perpendicular with respect to each other *dsa*(–)⊥ *dsb*(–) (Figure 1.3). To illustrate, a double helix (as in Figure 1.4 below, looking like a straightened-out version of the typical simplified diagram of a DNA double helix) can be projected onto any plane containing the axis of the plane such that the tangents of the resulting curves are perpendicular to one another at the points of intersection. (That is, projecting the two curves {(*x*,*y*,*z*): *x* = *r*⋅cos *t*, *y* = *r*⋅sin *t*, *z* = *kt*} and {(*x*,*y*,*z*): *x* = *r*⋅cos *t*, *y* = *r⋅*sin *t*, *z* = *k*(*t* + **)} onto the *x-z* plane, the tangents where the resulting plane curves meet at *z* = 0 are perpendicular to one another). By symmetry, this applies to all planes containing the *z* axis.

Thus, the average metric (1.23) corresponds to the segment "braid", consisting of two strands coiled around one another, *sa*(–)and*sb*(–), whoseprojections are perpendicular to one another. This section of the "double helix" can be described as a complex number

*dsab* (–)*=*(*dsa* (–)*+****i****dsb* (–)), (1.35)

which is equal to the square root of the module (1.34).

In connection with the above, we will call the averaged metric a "*k*-braid" (where *k* represents the number of threads). In particular, the averaged metric (1.23) is called "2-braid" as it is "coiled" from 2 lines *dsa*(–)and*dsb*(–).

Analogously, averaging metrics (1.17) and (1.18) leads to a "2-antibraid”.

 (1.36)

which describes the metric-dynamic state of the stable formation of a vacuum-type "air bubble in a liquid", but is a complete antithesis of the vacuum formation, describing a 2-braid (1.23).

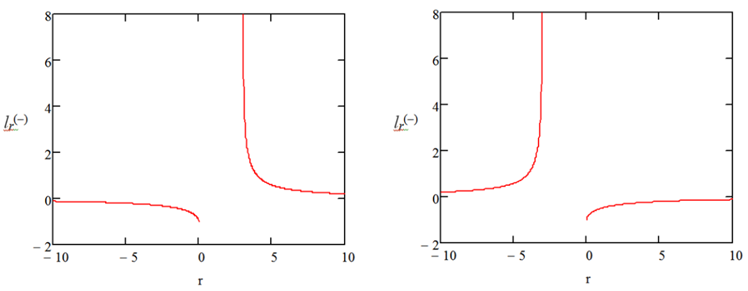
In such a case it behooves us to emphasize that the distance between two points *r*1 and *r*2 in the region with signature ( + + +) is determined by the expression.

The 2-braid (1.23) and 2-antibraid (1.36) fully complement one another, thereby yielding a solution of (1.21): *dsab*(–)2 + *dsab*(+)2 *= ds*(0)2. If we conditionally assume that the 2-braid (1.23) describes the metric-dynamic state of a stability "bulge" in the vacuum region (Figures 1.1 and 1.2), the 2-antibraid (1.36) describes exactly the same concavity to the same extent.

Substituting the components *gii*0() of metric (1.16) component and *g*11() of the metrics (1.14) or (1.15) into equation (1.32) leads to the absurd results shown in Figure 1.5[[3]](#footnote-3).

This once again confirms that averaging metrics (1.14)  (1.15) and/or (1.17)  (1.18) makes sense.

Now, based on development elsewhere (Gaukhman 2007/2017), we will discuss the metric-dynamic interpretation of zero metric tensor components *g*00(–) and *g*00(+).



**Fig.1.5.**  а) Graph of the function b) Graph of the function

; 

We introduce the usage of the terms "external" and "internal" (and related terms: outer, outside, inside, internal, etc.) to describe the same vacuum region by two metrics with mutually opposite signatures. The lengths in the local "external" and "internal" vacuum regions are given by pseudo-Euclidean metrics (1.16) and (1.19)

*ds*(–)2 = *с*2*dt*2 – *dr*2 – *r*2*dθ* 2 – *r*2sin2*θ* *dϕ* 2 = *сdt*′*сdt*′′– *dx*′*dx*′′– *dy*′*dy*′′– *dz*′*dz*′′, (1.37)

*ds*(+)2 = – *с*2*dt*2 + *dr*2+*r*2*dθ* 2+*r*2sin2*θ* *dϕ* 2 = – *сdt*′*сdt*′′+*dx*′*dx*′′+*dy*′*dy*′′+*dz*′*dz*′′. (1.38)

We introduce the terms for linear (affine) forms:

*ds*(–)′ = *сdt*′– *dx*′– *dy*′– *dz*′  "Cover" on the outer side of the vacuum; (1.39)

*ds*(–)′′ = *сdt*′′– *dx*′′– *dy*′′– *dz*′′  "Inversion" of the outer side of the vacuum; (1.40)

*ds*(+)′ = – *сdt*′+ *dx*′+ *dy*′+ *dz*′  "Cover" of the inner side of the vacuum; (1.41)

*ds*(+)′′ = – *сdt*′′+ *dx*′′+ *dy*′′+ *dz*′′ "Inversion" of the inner side of the vacuum. (1.42)

Let the "cover" and "inversion" of one side of the vacuum move relative to their axially fixed state along an axis *x* with the same velocity *vx*, but in different directions. This is formally expressed by the coordinate transformation:

*t*′= *t*, *x*′ = *x* + *vx t*, *y*′ = *y*, *z*′= *z*  For the "cover", (1.43)

*t*′′= *t*, *x*′′ = *x* – *vx**t*, *y*′′= *y*, *z*′′= *z*  For the "inversion". (1.44)

A consequence of the equality of the velocities *vx* in the modules of the "covers" and "inversions" due to the vacuum condition is that for every movement in the vacuum region there is a corresponding contrary movement (Gaukhman 2007/2008/2017).

Differentiating (1.43) and (1.44) and substituting the results of the differentiation to (1.37) and (1.38) in spherical coordinates we obtain metrics

*dsv*(–)2= (1+ *vr*(–)2/*с*2)*с*2*dt*2 – *dr*2 – *r2dθ* 2 – *r*2sin2*θ* *dϕ* 2, (1.45)

*dsv*(+)2= – (1+ *vr*(+)2/*с*2)*с*2*dt*2 + *dr*2 + *r*2*dθ* 2 + *r*2sin2*θ* *dϕ* 2, (1.46)

describing the kinematics of translational motion of the "external" and "internal" aspects of the local area vacuum extension. It then is under the vacuum conditions:

*dsv*(–)2 + *dsv*(+)2 = *ds*(0)2 = 0, (1.47)

The movement involved is compensated for by the contrary movement.

Compare *g*00(–) into the metrics (1.14) and (1.15) with *g*00(–) in the metric (1.45) and *g*00(+) in the metrics (1.17) and (1.18) with *g*00(+) in the metric (1.46) respectively obtain:

for the metric (1.14): 1– *r*0/*r* = 1+ *vr* (–*a*)2/*c*2 → *vr*(–*a*) 2 = – *c*2*r*0/*r* → *vr*(–*a*) = (– *c*2*r*0/*r*)½ ; (1.48)

for the metric (1.15): 1+ *r*0/*r* = 1+ *vr* (–*b*)2/*c*2 → *vr*(–*b*)2 = *c*2*r*0/*r* → *vr*(–*b*) = (*c*2*r*0/*r*)½ ; (1.49)

for t e metric (1.17): – (1– *r*0/*r*) = – (1+ *vr*(+*a*)2/*с*2) → *vr*(+*a*)2 = – *c*2*r*0/*r* → *vr*(+*a*) = (– *c*2*r*0/*r*)½; (1.50)

for the metric (1.18): – (1+ *r*0/*r*) = – (1+ *vr*(+*b*)2/*с*2) → *vr*(+*b*)2 = *c*2*r*0/*r* → *vr*(+*b*) = (*c*2*r*0/*r*)½ . (1.51)

These results suggest that the zero components *g*00(–) of the metrics (1.14) & (1.15) and *g*00(+) of the metrics (1.17) & (1.18) describe the motion of the relevant sub-layer vacuum region with speeds *vr*, as in (1.48) through (1.51), relative to their stationary state metrics given by (1.16) & (1.19).

Although we have movement, precisely what is moving in the vacuum state is not known, because there is no mechanism in the description of matter in geometrophysics to detect it. However, for convenience, in a vacuum such processes can be compared with the processes in the hypothetical layer of vacuum between two solids pressed together in a elastoplastic fluid.

**Terminology:** *We coin (as in (Gaukhman 2007/2008/2009/2017)) the terms "subcont", abbreviating "substantial continuum", and, correspondingly, “antisubcont” to designate the components of such an environment. The layers of the vacuum region are given in Table 1.1*.

Table 1.1

|  |  |  |  |
| --- | --- | --- | --- |
| *Metric/*  *signature* | *Number of metric* | *Meaning of coined terms* | *Side of vacuum* |
| *dsa*(–)2 (+ – – –) | (1.14) | *"a-subcont" - the outer side of the outer side of the vacuum region* | *E*  *X*  *T*  *E*  *R*  *N*  *A*  *L* |
| *dsb*(–)2  (+ – – –) | (1.15) | *«b-subcont" - the inner side of the outer side of the vacuum region* |
| *dsс*(–)2  (+ – – –) | (1.16) | *original flat outer side of the vacuum region (definite)* |
|  |  |  |  |
| *dsa*(+)2  (– + + +) | (1.17) | *"a-antisubcont" - the outer side of the inner side of the vacuum region* | *I*  *N*  *T*  *E*  *R*  *N*  *A*  *L* |
| *dsb*(+)2  (– + + +) | (1.18) | *"b-antisubcont"- the inner side of the inner side of the vacuum region* |
| *dsc*(+)2  (– + + +) | (1.19) | *original flat inner side of the vacuum region (definite)* |

Averaging the velocities given by (1.48) and (1.49), we find that the general movement of affine layers outside of the vacuum region (subcont) describes the average speed

*vrab*(–)(*r*) = ½[(*c*2*r*0/*r*)½ + *i*(*c*2*r*0/*r*)½], (1.52)

and the velocity average (1.50) and (1.51), leads to the average velocity

*vrab*(+)(*r*) =½[(*c*2*r*0 */r*)½ + *i*(*c*2*r*0 */r*)½]. (1.53)

which describes the average (total) movement of the affine layer of the inside of the vacuum region (of the antisubcont).

The modules of the complex functions (1.52) and (1.53) are equal

|*vrab*(–)(*r*)| = *c* (*r*0 */r*) ½, (1.54)

|*vrab*(+)(*r*)| = *c* (*r*0 */r*) ½, (1.55)

which shows that the average velocity in the affine layers of the outer and inner sides of the vacuum region (subcont and antisubcont) with *r*0 = *r* is close to , with *c* – the speed of light, but as the radius *r* increases greater than *r*0, the velocity decreases in proportion to 1/*r*½, approaching zero.

However, the squares of the velocities (1.48) and (1.49) are equal and opposite to one other *vra*(–)2=– *vrb*(–)2. Therefore, in the 2-braid (1.23), *g*00() = 1.

Similarly, the squared velocities (1.50) and (1.51) are equal and opposite each other *vra*(–)2 =–*vrb*(–)2. Therefore, in the 2-antibraidin(1.36), *g*00(+) = 1.

This fact leads to the stability of the considered vacuum relation, since the considering the amount of “subcont-flow" (similar to, but not to be confused with, flux), the amount of *a*-subcont “flowing in” is equal to the amount of *b*-subcont "flowing out".

It should be noted that some additive combinations of metrics (1.14) through (1.16) and/or (1.17) through (1.19) are different solutions of the nonlinear Einstein field equations (1.6), leading to a more balanced metric-dynamic description of the local centrally symmetric vacuum formation than any one of them individually. The kinematics and dynamics of the layers and the inside of the vacuum regions are discussed in detail elsewhere (Gaukhman 2007/2008/2009/2017).

**2. The second vacuum Einstein field equations and their solutions**

Considering the identity

∇*j gik*= 0, (2.1)

 (2.2)

Einstein added (1.1) another term (the so-called term)

 (2.3)

where  = ± 3/*ra*2 = constant, *ra* is the radius of the spherical vacuum formation.

In this case

 (2.4)

whence

 (2.5)

whereupon the equation (2.3) takes the form

 (2.6)

For 4-dimensional space: *n* = 4, *R* = 4Λ, equation (2.6) takes the most simple form

 or  (2.7)

Equations (2.7) will be called the second Einstein field equations.

Solutions to the second field equations (2.7) constitute the next set of metrics with signature (+   ) (i.e., for the conditional convex vacuum region:

, (2.8)

, (2.9)

, (2.10)

, (2.11)

; (2.12)

and with signature ( + + +) (that is, for the concave vacuum region):

 (2.13)

 (2.14)

 (2.15)

 (2.16)

. (2.17)

where *rb* is the constant of integration, analogous to *b* = *r*0 in the solutions (1.13).

We call metrics (2.8) through (2.17) “Kottler generalized metrics”. Departing from the metric expressed by (2.12) and (2.17) we obtain the special cases of the Kottler metrics (2.8) through (2.11) and (2.13) through (2.16), respectively, using *rb* = 0 and *ra* = .

The sum of all metrics (2.8) through (2.17) again leads to the metric (1.21), which is also a trivial solution of (2.7).

When *ra* =  and *rb* ≠ 0, the generalized Kottler metric described by the conjunction of (2.8) through (2.17) is transformed into the generalized Schwarzschild metric described by (1.14) through (1.19), while for *rb* = 0 and 1/*ra* = 1/*r*0 ≠ 0, the metrics (2.8) to (2.17) combine to become the deSitter metric:

1. to measure the convex vacuum region (bulge), with signature (+   ):

, (2.18)

 (2.19)

; (2.20)

bto measure the concave vacuum region (concavity) with signature ( + + +):

 (2.21)

 (2.22)

. (2.23)

When *ra* = *r*0, the metric described by the conjunction of (2.18) and (2.19) describes a closed convex (spherical) vacuum formation (i.e., the "core") in the range [0, *r*0] (Figure 2.1). This describes a region that has been defined as a vacuum cavity in the solution of the first vacuum equations (1.6) (Figure 1.2).

The arithmetic average of the two metrics (2.18) and (2.19) forms a 2-braid:

 (2.24)

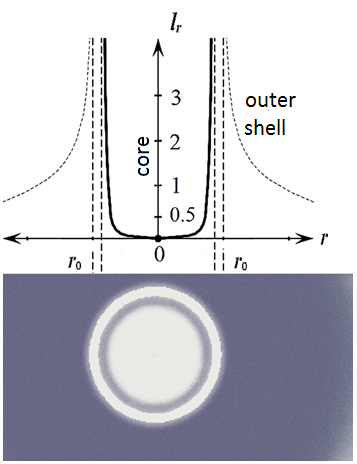
Substituting components *gii*0() and *gii*(), respectively, from (2.20) and (2.24) into (1.32), we obtain the relative lengthening of the one of side of vacuum

 , , . (2.25)

The function *lrc*(–) (the factor of expansion in the radial direction of the vacuum in the core) is shown in Figure 2.1.

In this case, a 4-braid *ds*1-4(–), for example, the helices *dsi*(–) of the four metrics (2.8) through (2.11) are formed and described via quaternions in (Gaukhman 2007/2008/2009/2017).

**Fig. 2.1** Graph of  *lrc*() function - elongation of the vacuum extension in the core (i.e. within a spherical cavity)



*ds*14(–) =(*ds*1(–) *+* **i***ds*2(–) + **j***ds*3(–)*+***k***ds*4(–)). (2.26)

Comparing *g*00() in the metrics (2.18) and (2.19) with *g*00() in the metric (1.45) and *g*00(+) in the metrics (2.21) and (2.22) and with *g*00(+) in the metric (1.46), we find the speed of movement of the vacuum layers at each point of the "core" of the vacuum formation (Figure 2.1).

for the metric (2.18): 1 + *r*2/*r*02 = 1+ *vra*(–)2/*c*2 → *vra*(–)2 = *c*2*r*2/*r*02 → *vra*(–) = *cr*/*r*0 ; (2.27)

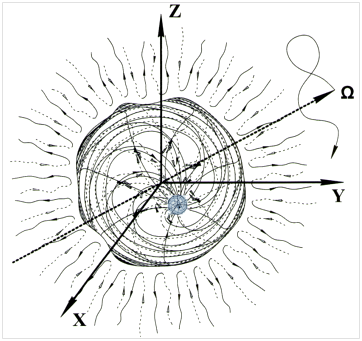
for the metric (2.19): 1 – *r*2/*r*02 = 1+ *vrb*(–)2/*c*2 → *vrb*(–)2 = –*c*2*r*2/*r*02 → *vrb*(–) = – *cr*/*r*0 ; (2.28)

for the metric (2.21): – (1+ *r*2/*r*02) = – (1+ *vra*(+)2/*с*2) →  *vra*(+)2 = *c*2*r*2/*r*02  → *vra*(+) = *cr*/*r*0 ; (2.29)

for the metric (2.22): – (1 – *r*2/*r*02) = – (1+ *vrb*(+)2/*с*2) → *vrb*(+)2 = –*c*2*r*2/*r*02  → *vrb*(+) = – *cr*/*r*0. (2.30)

From the expression (2.27) through (2.28) of the movements in mutually opposite directions, we find that the speed of the vacuum layers *vra*(–) = – *vrb*(–) in the center of the core (at *r* = 0; Figure 2.1) is zero, and on the periphery of the "core" with radius *r*0, they move with the speed of light *c*.

More important than this situation are those when the core of the vacuum formation revolves. However, according to the classification given in the Table 1.1, a subcont rotates in the periphery of the core at the speed of light *vra*(–)(*r*0) = *с* (Figure 2.2). It then describes a helix, slowing down as it approaches the center of the core, almost stopping, *vra*(–)(0) = 0, as it is converted into a *b*-subcont. In its turn, the *b*-subcont flows in a winding fashion from the core of the center of the acceleration, starting from the speed *vrb*(–)(0) = 0 and ending by rotating on the periphery of the "core" (*r*0) with the speed of light, *vrb*(–)(*r*0) = *с* (Figure 2.2), where it is converted into an *a*-subcont. Thus, the intracore *ab*-subcont "processes" the loop, and support the strongly deformed periphery of the core of the vacuum formation (Figure 2.1) at a steady state.



**Fig. 2.2** Rotation of the core of the vacuum formation

**3. The non-Riemannian geometry with torsion and rotation**

In the previous section, it was noted that the study of stable vacuum entities should take into account the rotation of their "core", therefore touch on some aspects of geometry with torsion and rotation.

Of all non-Riemannian geometries, one of the most important is the geometry of Riemann-Cartan space with absolute parallelism, which was often used by Einstein (Einstein 1928). The Riemann-Christoffel curvature tensor uses this, as given in (Ivanenko, Pronin, Sardanashvily 1985). We the curvature equal to zero as follows:

 (3.1)

where the Riemann curvature tensor is and the other terms are based on the contortion tensor, using the lowering of the indices via

, (3.2) 

which in its turn is based (by lowering of the indices) on the torsion tensor

.  (3.3)

The identity (3.1) means that in absolute parallelism geometry, the components of the Riemann curvature tensor are fully compensated by torsion. In this case, instead of (2.7) in the geometry based on the variational principle, one obtains the Einstein-Cartan equation (Ivanenko, Pronin, Sardanashvily 1985)

 (3.4)

where  (3.5)

is the Cartan-Schouten tensor;  is the trace of the contortion tensor.

This equation looks as if the torsion of space, or rather the rotational inertia as explained in (Shipov 1997), is the source of its curvature. Investigating more closely, one sees that the converse is the case, whereby the curvature of space is the source of its torsion.

In the works of R. Vaytsenbeka, D. Vitali and G. Shipov, absolute parallelism geometry also received full geometrized treatment using the equation (Shipov 1997)

 (3.7)

where the right side is expressed in the formal terms of reference:

 (3.8)

is theVaytsenbek -Vitali-Shipov tensor;

 (3.9)

is the Ricci rotation coefficients;

 (3.10)

is the non-holonomicity object; *eak*are components of the unit vector of a rotating 3-D reference basis.

Different approaches by Cartan - Schouten and Vaytsenbek - Vitali - Shipov to constructing geometries with torsion and rotation characterize the different types of rotational space. If the *Yμν* tensor characterizes the motion vector at the start of the trial and the curved region of the rotating vacuum, the tensor *Фik* characterizes the torsional rotation around the center of reference in 3 dimensions (Shipov 1997).

In general, the equation is fully geometrized

 (3.11)

However, existence not equal to zero of the right-hand sides of equations (3.6), (3.7) and (3.11) leads inevitably to an unstable condition of the vacuum region, because tensors *Yμν* and *Fμν* are both nonzero, so that they obey:

, (3.12)

instead of the law of conservation

∂(Y*ik* + *Фik* )*/*∂*xk* = 0, (3.13)

Thus, for stable vacuum formations all the components of the Cartan-Schouten tensor *Yμν* and the Vaytsenbek-Vitali-Shipov tensor *Фik* should be equal to zero. Thus the identity (3.11) falls into a system of two or three equations

  (3.14)

It is important to note that in Riemann-Cartan, space is unbalanced due to the asymmetry of the Christoffel symbol and the Ricci tensor *Rμν* ≠ *Rνμ*. But in the particular case of Λ = 0, *Yμν*= 0 and *μν* = 0 (or *Y*μν + *μν* = 0) of the equations (2.5) and (3.11), *Rμν* = 0 and *Rνμ* = 0, so they are identically equal.

This corresponds to these types of spins and vacuum twists which do not affect the Ricci tensor *Rμν*, but they can influence the curvature tensor components. It seems that a certain amount of space is rotated with respect to the external observer, but those who are within its scope almost do not feel this rotation. As a rough example, it is very difficult to feel that the Earth's surface rotates for those on it. However, there are effects indicating the presence of inertial forces caused by the rotational motion of the planet, for example, the apparent deviation of the pendulum of Foucault, the different slopes of the left and right banks of rivers, etc. It is this type of rotation of the core of the vacuum formation that we have treated in Section 2 (Figure 2.2).

**4. Advanced (third) Einstein field equation**

Up to this point we have considered well-known solutions for the Einstein field equations (1.6) and (2.7). We are now ready, for the first time, to consider an expanded version of these equations.

Due to the properties of the components of the metric tensor (2.1), it is easy to show that

∇*j* Λg*ik* = Λ∇*j gik* = 0. (4.1)

The equality

 (4.2)

where 1, 2, ... , ∞ are constants, is also clear. Therefore, guided by the same considerations that led Einstein to introduce  as a member of equation (2.3), we can write

 (4.3)

or

 (4.4)

where *rk* is the radius of the *k*th spherical vacuum formation.

Equation (4.4) can meet all the requirements to satisfy the equation (2.3) if 1+2+...+∞ = Λ0 (i.e. if the given series converges to Λ0). Indeed, in this case, equation (4.4) reduces to the form (2.3)

 (4.5)

Combining (4.4) with *gik*, we get

 (4.6)

whence

 (4.7)

Substituting (4.7) in (4.6) for *n* = 4 we obtain the simplest (for this case) version to expand the Einstein field equation

 (4.8)

This expression will be called the "third Einstein field equation".

The series in equation (4.4), taking into account (4.7) and *n* = 4, converges to *R*/4 either:



absolutely:

(4.9)



1. conditionally or sign-variable:

:

(4.10)

where *Nk* represents a sequence of numbers.

Of particular interest is the average of the Ricci-flat vacuum region from *Rik* = 0 because of its correlation with Ricci-flat Calabi-Yau spaces. In this case, according to (4.7) and (4.8)  and *R* = 0, the system of equations (3.14) breaks up into a system of two or three equations:

  (4.11)

**5. Solutions of the third Einstein field equations**

Consider the most important (in the opinion of the author) case when the third Einstein field equation (4.8) has the form

, (5.1)

where  (5.2)

is an alternating series which is equal to zero.

First of all, we find the solution of equation (4.8) with:

 (5.3)

where (5.3) coincides with the second Einstein field equations (2.7). Therefore, the solutions of (5.3) are generalized Kottler metrics for the formation of a convex vacuum region (formations), the metrics (2.8) through (2.17), all of which havesignature (+   ):

, (5.4)

, (5.5)

, (5.6)

, (5.7)

; (5.8)

or signature ( + + +) for a concave vacuum formations

, (5.9)

 (5.10)

 (5.11)

 (5.12)

 (5.13)

where , (5.14)

 (5.15)

whereby we may substitute *b = rf*in the solution to (1.13).

Further will be considered two private, but, in the author's opinion, important cases which we will conditionally call "Hierarchy of ten spheres" and "Lucas-Fibonacci Branches".

**Terminology:** *The two cases* *may appear isolated, but together their solutions relate to one another in ways yielding unexpectedly fruitful results. The author considers these important enough to baptize them with names. Just as Gell-Mann could allude to a term from Buddhism to coin his Eightfold Way, so too we allude to a couple of terms out of an ancient Jewish tradition in order to coin our terms for the organization presented in the next two sections. The first set of results (Section 6) is dubbed the "Hierarchy of ten spheres", while the second (Section 7) is baptized “Lucas-Fibonacci Branches".*

**6. Hierarchy of ten spheres**

We investigate the special case where the series (5.14) and (5.15) have the simple form:

 (6.1)

 (6.2)

Consider a series of separate positive and negative terms

,  (6.3)

,  (6.4)

We substitute the series (6.3) in the metric (5.4) through (5.7) instead of the series (5.14) and (5.15) and take into account that we can write

 (6.5)

 (6.6)

 (6.7)

 (6.8)

The result is a metric with signature (+   ):

 (6.9)

 (6.10)

 (6.11)

 (6.12)

 (6.13)

Similarly, substitution of series (6.4) in the metric (5.10) through (5.13) affords metrics with the antipodal signature ( + + +):

 (6.14)

 (6.15)

 (6.16)

 (6.17)

 (6.18)

We now consider what the radii *rk* in the metric expressed by (6.5) through (6.18) may equal. It is natural to assume that in a fully geometrized physics only geometric constants must be present. These constants may include: *Rv*, the parametric radius of the universe; and *lс ≈ с* Δ*t ≈ с* · 1 sec *≈* 2,9·1010 cm that is, the distance traveled by the beam of light in a vacuum during a single time interval Δ*t* = 1 second.

Assuming that the radii *rk* in the metric (6.5) through (6.18) is estimated as the ratio

*rk ~ Rv*2*/lсk* ,

where *lсk =* (2,9·1010) *k* cm is the distance obtained by the construction of 2,9·1010 raised to the power of *k*. If we assume that *Rv ≈* 1025 cm, we get the approximate relation

cm, (6.19)

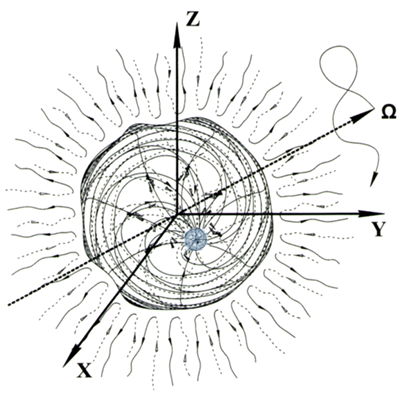
which implies a hierarchical sequence of the radii of the ten spheres.

**Terminology:** *Before proceeding, we must note that some of the entities here are analogues to, and sometimes overlapping with, measurements related to measurable subatomic particles, although the new entities are more general and not necessarily directly measurable, for the moment only appearing in calculations. (We leave aside the philosophical considerations as to whether all terms in a calculation must correspond to a real physical entity when the end result is just the same. The recurring debate on the “reality” of the wave function is an example that both sides have a basis to justify their positions. As well, many terms graduate from purely mathematical entities to representations of real entities, such as was the case with the positron, the neutrino, and countless other entities that we regard today as real).*

*In the framework of the Algebra of Signatures (“Alsigna”), the names of the individual particles are put into guillemets, for exampel: «electron», «muon», etc. In this way metric-dynamic models of given local vacuum entities of Alsigna are clearly distinguished from the corresponding particles in the Standard Model and in String Theory.*

*The usual analysis breaks up an entity into sub-entities, which are then broken down in their turn, each layer using a different structure until one arrives at elementary particles. The structure proposed in this paper, on the other hand, is available at all levels, even for the elementary particles.*

*The terms for the constituents at one layer below the «particles», use one coined word: “particelle” (coined from “particle” and “organelle”), and three other terms: “scope”, “outer shell ”, and “abyss”; the usage of these latter three terms should be clearly distinguishable by the context from those of other contexts. In fact, it would be more useful to consider these as structures, applicable to a wide variety and scale of physical entities, than as particles. This difference is emphasized in the list below (6.20). The reader will immediately note in that list, whereas many of the numbers could correspond to directly measurable quantities, others clearly do not. For example, lengths are given that are beyond the range of measurement: bigger than the observable universe, and smaller than the Planck distance.*

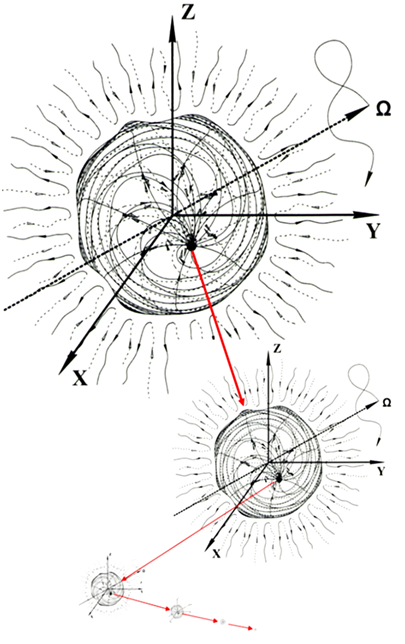


**Fig. 6.1**. The sequence of nested spherical vacuum formations

*Of course, we could have left each rk named simply “rk” for respective values of k. However, we hope that the names assigned will serve as an aid to intuition, whereby one should not take the names any more literally Lengths r2 through r6 are within an order of magnitude of well-known physical measurements.*

*Furthermore, we do not use a zero length for any particle, because we do not really use particles in the classic sense. After all, particles are defined as stable local deformations of vacuum. We uses the word “particle” for convenience, although it is stable area of strong deformations and bound intra-vacuum currents.*

With this lengthy preamble, we may now proceed by approximate recurrence relation (6.19):



**Fig. 6.2**. Hierarchy of ten nested spherical vacuum formations

*r*1 ~ 3,4·1039 cm: ~ «Universe» inner core ; (6.20)

*r*2 ~ 1,2·1029 cm: ~ «metagalaxy» inner core;

*r*3 ~ 4·1018 cm: ~ «galaxy» inner core;

*r*4 ~ 1,4·108 cm: ~ «star» or «planet» inner core;

*r*5 ~ 4,9·103 cm: ~ biological «cage» inner core;

*r*6 ~1,7·1013 cm: ~ core of an elementary «particle»;

*r*7 ~ 5,8·1024 cm: ~ core of an «protoquark»;

*r*8 ~ 2,1·1034 cm: ~ core of an «plankton»;

 *r*9 ~ 7·1045 cm: ~ core of an «phytoplankton»;

*r*10 ~ 2,4·1055 cm: ~ core of an «instanton».

Metrics (6.5) through (6.17) are the solutions of the simplified third Einstein vacuum equations (5.1)

, (6.21)

where  

In the hierarchy of the radii *r*k (6.20), these solutions describe a sequence of nested spherical vacuum formations (Figures 6.1, 6.2).

For example, consider one of the vacuum degree of the hierarchy (6.20) with a radius *r*6 ~ 1,7·1013 cm corresponding to the characteristic size of the "core" of “elementary particles”. All other vacuum formations of the hierarchy considered here (6.20) are arranged similarly.

*The radius of the core of such a formation is almost the same as the Thompson scattering length (aka the Lorenz radius). Despite the fact that the Thompson scattering length, 2,8·1013 cm, is unrelated to the actual size of the electron, it is called the “classical radius of the electron”. Since this length is the same order of magnitude of the value for the radius r6 ≈ 1,7·1013 cm of this formation, we find it fitting to dub the «particle» at this scale the «electron». Our further constructions, once the other «particles» are in place, will further justify this decision.*

In the metrics (6.9) through (6.12) will leave only those composed which contain radii *r*6. As a result, we obtain the following multilayer metric-dynamic model of «electron» (i.e. convex vacuum formation) with a core radius almost equal to "the classical radius of electron" *r*6 ≈ 2,8·10-13 cm.

**«Electron»** (6.22)

The «electron» is a convex multilayer vacuum formation

with signature

(+ – – –)

consisting of:

**[a] Тhe outer shell of the «electron»**

in the interval [*r5, r6*] (Figure 6.3)

, (6.23)

, (6.24)

, (6.25)

; (6.26)

**[b] The core of the «electron»**

in the interval [*r*6*, r*7]

(Figure 6.3)

, (6.27)

, (6.28)

, (6.29)

; (6.30)

**[c] The scope of the «electron»**

in the interval [0*,* ∞]

. (6.31)

Similarly, the metrics (6.13) through (6.17) retain only those terms that contain radii *r*6. As a result, we obtain the following convention for a metric-dynamic model of a concave vacuum formation which we will dub an «positron» (exact antipode to an «electron»):

**«Positron»** (6.32)

The «positron» is a concave vacuum formation

with the signature

( + + +)

consisting of:

**[a] The outer shell of the «positron»**

in the interval [*r*5, *r*6]

(Figure 6.3)

, (6.33)

, (6.34)

, (6.35)

, (6.36)

**[b] The core of the «positron»**

in the interval [*r*6, *r*7]

(Figure 6.3)

, (6.37)

, (6.38)

, (6.39)

, (6.40)

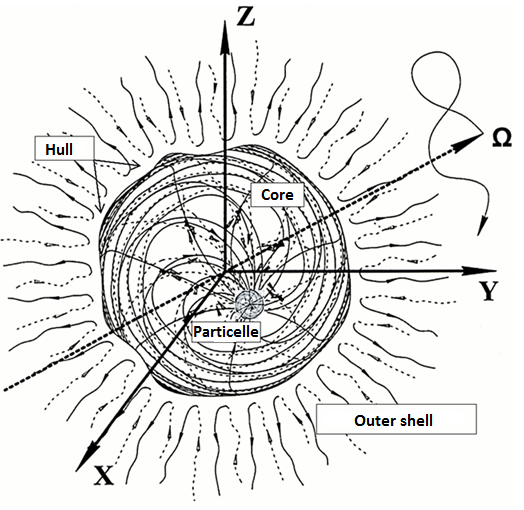
**[c] The scope of the «positron»**

in the interval [0, ]

; (6.41)



**Fig. 6.3** Outer shell, abyss, core and the internal particelle of the elementary «particle»



**Abyss**

Figure 6.3 shows a geometricized model of a spherical vacuum formation with subformations, using radii of the hierarchy (6.20). Taking, for example, the «electron» (or its antipode, the «positron»), the formation represented in Figure 6.3 would have: a "core" with a radius *r*6 ~ 1,7·1013 cm; an inner particelle with a radius *r*7 ~ 5,8·1024 cm and an outer shell extending from *r*6 ~ 1,7·1013 cm to *r*5 ~ 4,9·103 cm (or to *r*4 ~ 1,4·108 cm, or up to *r*3 ~ 4·1018 cm, etc., depending on in which spherical formation there is an core of the «electron»).

In another case, for example, «planet» inner core has a radius *r*4 ~ 1,4·108 cm; its particelle has the radius *r*5 ~ 4,9·103cm (or, *r*6 ~ 1,7·1013 cm, etc., depending on which spherical formation is found in the «planet» inner core) and the outer shell extends from *r*4 ~ 1,4·108 cm to *r*3 ~ 4·1018 cm (or until *r*2 ~ 1,2·1029 cm, or up to *r*1 ~ 3,4·1039 cm).

The "scope" (6.31) or (6.41) of a spherical vacuum formation begins at the center and ends at infinity. The scope represents a kind of memory of the undeformed portion of the considered vacuum area. It is almost as if it does not exist in the curved portion of the vacuum state, but according to equation (1.32), the relative elongation and deformation of the vacuum section cannot be determined without the *gii*0(–) of the scope.

Тhe «abyss» (Figure 6.3) is a spherical boundary between the core and the outer shell of any spherical vacuum formation.

**7. Lucas-Fibonacci branches**

We return to the series (5.2)

. (7.1)

Among the many numerical sequences, the familiar Fibonacci sequence, 0,1,1,2,3,5,8,11... occupies a special place. It may be extended to the negative numbers, yielding the less familiar “negafibonacci numbers”:

|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| F8 | F7 | F6 | F5 | F4 | F3 | F2 | F1 | F | F | F | F | F | F | F | F | F |
| 21 | 13 | 8 | 5 | 3 | 2 | 1 | 1 | 0 | 1 | 1 | 2 | 3 | 5 | 8 | 13 | 21 |

(7.2)

We can also modify it to “seed” the beginning two numbers of the recursion, using 0 and –1 for the seeds, yielding

... 21,–13, 8, –5, 3,–2,1,–1, 0,–1,–1,–2,–3,–5,–8,–13,–21... (7.3)

All of these follow the recursion relation

*Fn*= *Fn*1 + *Fn*2.

We may now use the negafibonacci numbers for our sequence *Nk* in the series (7.1), labeling the *n*th term in the sequence *Fn* for integer *n*, yielding

. (7.4)

Also Lucas numbers can be used, which are defined by the recurrence formula

*Ln=Ln*1 *+Ln*2  for *L*0= 2 and *L*1= 1; or , (7.5)

where the golden section Phi, .

One example of a Lucas sequence occurs by using the values 2 and 1 for *n* = 0, 1:

*Ln:* 2, 1, 3, 4, 7, 11, 18, 29, 47, 76, 123, 199, 322, … (7.6)

In this case, (7.1) can take the form

. (7.7)

Taking into account the third Einstein field equations (7.4) and (7.7), the equation (5.1) can be written as  (7.8)

Since the conditions (7.4) and (7.7) are similar to (5.2), the solution of equation (7.8) will be similar to the solution of equation (5.1). The difference is that in the metrics (5.4) through (5.13) one should not substitute the series from (5.14), but rather, for the general case, the series

 (7.9)

It is necessary to expect that the vacuum equations may include the Fibonacci numbers *Fn*, the Lucas numbers *Ln* and *φ* (the golden section), as they contribute to the harmony of so many other phenomena in nature. We follow up on this expectation.

Combining the results of this and previous points, we arrive at the following model of the physical universe: the hierarchical sequence of tenspheres with radii *rk* (6.20) acts as a "trunk" and the solutions of equation (7.8) look like Lucas-Fibonacci branches radiating in all directions from this grand trunk.

Now we may ponder the following question. If the right sides of the Einstein field equations (1.6), (2.7) and (4.8) are equal to zero, leading to a state with no mass, what, then, fills the void?

In the framework developed here, this void is filled with a variety of spherical convex and concave vacuum formations with different radii, which interact with each other by means of vacuum currents. This is, however, not ether or Descartes’ vortices, as we shall outline in the following outline. A full exposition of the relationship between the fundamental forces (electromagnetic, nuclear and gravitational) and the spherical vacuum formations of different scales would stretch this paper beyond reasonable limits; articles by Gaukhman present a fuller exposition (Gaukhman 2007/2008/2009).

**8. The elements of the Algebra of signatures**

We return to the metrics (1.16) and (1.19), which for brevity can be represented in a Cartesian coordinate system:

*ds*(+ – – –)2 *= с*2*dt* 2*– dx*2*– dy* 2 *– dz*2 = *x*02 *–* *x*12 *– x*22 *–* *x*32 = 0 with signature(+ – – –),(8.1)

*ds*(– + + +)2 *= – с*2*dt* 2*+ dx*2*+ dy* 2 *+ dz* 2 = *– x*02 + *x*12 + *x*22 + *x*32 = 0with signature( + + +).(8.2)

Here we use the following conventions:

*s*(+ – – –)2 = *ds*(–)2, *s*(– + + +)2 = *ds*(+)2, *x*02 = *с*2*dt* 2, *x*12 *= dx*2, *x*22 *= dy* 2, *x*32= *dz*2.(8.3)

These metrics are solutions at the same time all three vacuum equations (1.6), (2.7) and (4.8).

In addition to the metrics (8.1) and (8.2) with signatures (+ ) and ( + + +), 14 other possible metrics can be written with the corresponding signatures:

|  |  |  |  |
| --- | --- | --- | --- |
| *s*(+ + + +)2 =*x*02 + *x*12 + *x*22 + *x*32 =0 |  | *s*(– – – – )2 = – *x*02 – *x*12 – *x*22 – *x*32 =0 |  |
| *s*(– – – +)2 = – *x*02 – *x*12 – *x*22 + *x*32 =0 |  | *s*(+ + + –)2 =*x*02 + *x*12 + *x*22 – *x*32 =0 |  |
| *s*(+ – – +)2 = *x*02 – *x*12 – *x*22 + *x*32 =0 |  | *s* (– + + –)2 = – *x*02 + *x*12 + *x*22 – *x*32 =0 |  |
| *s*(– – + –)2 = – *x*02 – *x*12 + *x*22 – *x*32=0 | (8.4) | *s*(+ + – +)2 = *x*02 + *x*12 – *x*22 + *x*32 =0 | (8.5) |
| *s*(– + – –)2 = – *x*02 + *x*12 – *x*22 – *x*32 =0 | *s*(+ – + +)2 = *x*02 – *x*12+ *x*22 + *x*32 =0 |
| *s*(+ – + –)2 = *x*02 – *x*12 + *x*22 – *x*32 =0 |  | *s*(– + – +)2 = – *x*02 + *x*12 – *x*22 + *x*32 =0 |  |
| *s*(+ + – –)2 = *x*02 + *x*12 – *x*22 – *x*32 =0 |  | *s*(– – + +)2 = – *x*02 – *x*12 + *x*22 + *x*32 =0 |  |
| *s*(+ – – –)2 = *x*02 – *x*12 – *x*22 – *x*32 =0 |  | *s*(– + + +)2 =– *x*02 + *x*12 + *x*22 + *x*32 =0 |  |

Operations on the metrics (8.4) and (8.5) will be carried out componentwise, so we will call such

aggregate metrics "ranks" (Gaukhman 2007).

Instead of the uniform terms in the ranks (8.4) and (8.5) being summed up directly, they can be summed up using only signs preceding these terms. So for brevity, instead of ranks (8.4) and (8.5), we can use the following equivalent ranks:

|  |  |  |  |
| --- | --- | --- | --- |
| (+ + + +)  (– – – + )  (+ – – + )  (– – + – )  (+ + – – )  (– + – – )  (+ – + – )  (+ – – –)+ | +  +  +  +  +  +  +  + | (– – – – )  (+ + + – )  (– + + – )  (+ + – +)  (– – + +)  (+ – + +)  (– + – +)  (– + + +)+ | = 0  = 0  = 0  = 0 (8.6)  = 0  = 0  = 0  = 0 , |

The subscripted sign after the brackets (...)+ indicates what operation is done with the numbers corresponding to the characters in the columns and/or rows; that is, (...)+ foraddition, (...)for subtraction, (...) for division and (...)× for multiplication. Although the other operations could be also defined componentwise, excluding division by zero, we shall not do so here, as presently we are only concerned with addition.

The metrics with the above features, as ranked in (8.4) and (8.5), are not solutions of the Einstein field equations (1.6), (2.7) and (4.8). This can be verified by direct substitution of the metric tensor components of these metrics in the corresponding equations.

However, regard the result from, for example, summing (as earlier explained) the first seven metrics of the ranking (8.4); it is the metric with signature (+   ): *s*(+ – – –)2 = *x*02 – *x*12 – *x*22 – *x*32 = 0. (In order to make this calculation, one can simply add up the respective columns.)

Similarly, the sum of the first seven metrics ranked by (8.5) is wound with the opposite metric signature ( + + +): *s*(– + + +)2 =– *x*02 + *x*12 + *x*22 + *x*32 = 0.

Therefore, vertically summing up the seven metrics of (8.4) and/or (8.5), leads to solutions of the Einstein field equations (1.6), (2.7) and (4.8):

(8.7)

*ds*(+– – –)2 = *ds*(+ + + +)2 + *ds*(– – – +)2  + *ds*(+ – – +)2 + *ds*(– – + –)2 + *ds*(+ + – –)2 + *ds*(– + – –)2 + *ds*(+ – + –)2 ,

*ds*(– + + +)2 = *ds*(– – – – )2 + *ds*(+ + + –)2 + *ds* (– + + –)2 + *ds*(+ + – +)2+ *ds*(– – + +)2 + *ds*(+ – + +)2 + *ds*(– + – +)2.

The same is true of horizontal sums of the above. For example,

*ds*(+ – – +)2 + *ds* (– + + –)2 = 0*∙с*2*dt*2*+* 0*∙dr*2 *+* 0*∙* *dθ* 2*+* 0*∙*sin2*θ dϕ* 2 = *ds* (0 0 0 0)2, (8.8)

In addition, the sum of all 16 metrics of (8.4) and (8.5) is a solution of the given vacuum equations

*ds*Σ2 = *ds*(+ – – –)2 + *ds*(+ + + +)2 + *ds*(– – – +)2 + *ds*(+ – – +)2 +

+ *ds*(– – + –)2 + *ds*(+ + – –)2 + *ds*(– + – –)2 + *ds*(+ – + –)2 + (8.9)

+ *ds*(– + + +)2 + *ds*(– – – – )2 + *ds*(+ + + –)2 + *ds*(– + + –)2 +

+ *ds*(+ + – +)2 + *ds*(– – + +)2 + *ds*(+ – + +)2 + *ds*(– + – +)2 = *ds* (0 0 0 0)2 = 0.

An equivalent representation of a signature of expression (8.9) has the form

(+ – – –) + (+ + + +) + (– – – +) + (+ – – +) +

+ (– – + –) + (+ + – –) + (– + – –) + (+ – + –) + (8.10)

+ (– + + +) + (– – – –) + (+ + + –) + (– + + –) +

+ (+ + – +) + (– – + +) + (+ – + +) + (– + – +) = {0 0 0 0}.

A structure based on these ranks takes the form of “vacuum conditions":

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| 0 =  0 =  0 =  0 =  0 =  0 =  0 =  0 =  0 =  0 = | ( 0 0 0 0)  (+ + + +)  (– – – + )  (+ – – + )  (– – + – )  (+ + – – )  (– + – – )  (+ – + – )  (– + + +)  (0 0 0 0) + | +  +  +  +  +  +  +  +  +  + | (0 0 0 0)  (– – – – )  (+ + + – )  (– + + – )  (+ + – +)  (– – + +)  (+ – + +)  (– + – +)  (+ – – –)  (0 0 0 0) + | = 0  = 0  = 0  = 0  = 0  = 0  = 0  = 0  = 0  = 0 |

(8.11)

This process could be called "splitting of zeros” (Gaukhman 2007).

The seventeen signatures (8.10) form a structure as indicated in the above introduction to the Algebra of signatures. A further structure which is developed in the cited references can be created by adding the Kronecker product and using the formation of the sixteen non-zero signatures of the ranked (8.11) in the anti-symmetric matrix resulting from the square using the Kronecker product of a 2 × 2 matrix of binary signatures (Gaukhman 2007/2017):

 (8.12)

We shall not follow up on this possibility in this paper; the reader is referred to the papers alluded to above.

According to the classification of Felix Klein, quadratic forms (8.4) and (8.5) are divided into three topological classes (Klein 2004):

**1st class**: quadratic forms (metric), the signatures of which are composed of four identical characters:

*x*02  + *x*12 + *x*22 + *x*32 = 0 (+ + + +) (8.13)

– *x*02  – *x*12 – *x*22 – *x*32 = 0 (*–* *–* *–* *–*) (8.14)

represent a"null" 4-metric space. In these spaces, there is only one actual point that is at the beginning of the light cone. All other terms of these extents are imaginary. In fact, in this case the metric (8.13) does not describe a positive length but rather a single point (which we will term a "white" point); and the metric (8.14) describes a single anti-point (which we shall term a "black" point).

**2nd class**: metrics, whose signatures are composed of three identical symbols and one of the opposite:

– *x*02  –*x*12 – *x*22 + *x*32 = 0 (*–* *–* *–* +)

– *x*02 – *x*12 + *x*22 – *x*32 = 0 (*–* *–* + *–*)

– *x*02  + *x*12 – *x*22 – *x*32 = 0 (*–* + *–* *–*)

*x*02 – *x*12 – *x*22 – *x*32 = 0 (+ *–* *–* *–*)

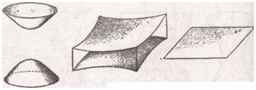
*x*02 + *x*12 + *x*22 – *x*32 = 0 (+ + + *–*)

*x*02 + *x*12 – *x*22 + *x*32 = 0 (+ + *–* +)

*x*02 – *x*12 + *x*22 + *x*32 = 0 (+ *–* + +)

– *x*02 + *x*12 + *x*22 + *x*32 = 0 (*–* + + +)

(8.15)



is an oval with four surfaces (Klein 2004): a) ellipsoid; b) elliptic paraboloid; c) two-sheeted hyperboloid (elliptic hyperboloid).

**3rd class**: metrics, the signatures of which are composed of two positive and two negative signs:

*x*02 – *x*12 – *x*22 + *x*32 = 0 (+ *–* *–* +)

*x*02 + *x*12 – *x*22 – *x*32 = 0 (+ + *–* *–*)

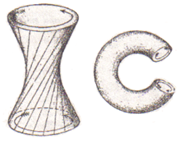
*x*02 – *x*12 + *x*22 – *x*32 = 0 (+ *–* + *–*)

– *x*02 + *x*12 + *x*22 – *x*32= 0 (*–* + + *–*)

– *x*02 – *x*12 +*x*22 + *x*32 = 0 (*–* *–* + +)

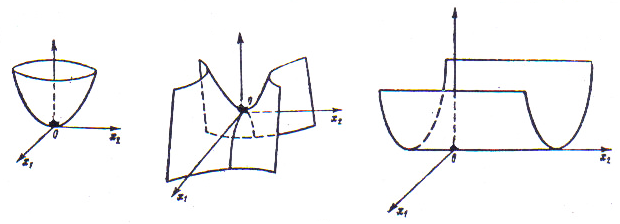
– *x*02 + *x*12 – *x*22 + *x*32 = 0 (*–* + *–* +)

(8.16)



These represent a variety of options for annular surfaces (Klein 2004): (a) single-band hyperboloids; (b) hyperbolic paraboloids.

A simplified illustration of the signature due to its topology of the 2-dimensional region is shown in Figure 8.1.

**** a) *sign* (+ +);b) *sign* (**–** +); c) *sign* (+ 0)

*z* = *x*12 + *x*22*z* = *x*22 **–** *x*12*z* = *x*12

**Fig. 8.1** Signature of the metric connection with the topology of 2-dimensional length (Klein 2004)

Such an additive overlay (or "atlas") of a 7-metric space with metrics (8.4) and (8.5) leads to the Ricci-flat spaces with the total metrics (8.1) and (8.2). Such a 7-sheeted atlas is very similar to the Ricci-flat 10-dimensional Calabi-Yau space.

Stability can only be:

* a convex vacuum formation, described by a metric with signature (+   ),
* a concave vacuum formation described by a metric with signature ( + + +),
* a “flat" vacuum formation, described by a metric with signature (0 0 0 0).

All the other 14 metrics (8.4) and (8.5) with the signatures of the numerators are ranked by (8.6)

|  |  |  |
| --- | --- | --- |
| (+ + + +)  (– – – + )  (+ – – + )  (– – + – )  (+ + – – )  (– + – – )  (+ – + – ) |  | (– – – – )  (+ + + – )  (– + + – )  (+ + – +)  (– – + +)  (+ – + +)  (– + – +) (8.17) |

describe various types of "convex-concave" states. The corresponding regions of the vacuum may not be stable, since metric data cannot be solutions of vacuum equations. They can occur as temporary complex distortions of a local vacuum area, but after some time they disappear or turn into other types of fluctuations with other signatures (or topologies).

However, if the additive superposition of several metrics with signatures (topologies) in the sum as in (8.17) leads to an average of convex vacuum formations with the signature (+   ), or in the concave average vacuum formation with the signature ( + + +), or in the "flat" average vacuum formation with the signature (0 0 0 0), then the corresponding vacuum degree may be stable.

**9. The «proton»  «antiproton»**

Solutions of Einstein field equations (1.6), (2.7) and (4.8) lead not only to aggregate metrics (8.4) and(8.5), but, for example, also to additive combinations of metrics:

|  |  |
| --- | --- |
| сигнатурами.ких протяженностей с различными сигнатурами.*s*(– – – +)2 =– *x*02 – *x*12 – *x*22 + *x*32 =0  *s*(+ – + – )2 = *x*02 – *x*12 + *x*22 – *x*32 =0 (9.1)  *s*(+ + – –)2 = *x*02 + *x*12 – *x*22 – *x*32 =0  *s*(+ – – –)2 = *x*02 – *x*12 – *x*22 – *x*32 =0 | *s*(+ + + – )2 = *x*02 + *x*12 + *x*22 – *x*32 =0  *s*(– + – +)2 =– *x*02 + *x*12 – *x*22 + *x*32 =0 (9.2)  *s* (– – + + 2 = – *x*02 – *x*12 + *x*22 + *x*32 =0  *s*(– + + +)2 =– *x*02 + *x*12 + *x*22 + *x*32 =0 |

There are three possibilities for the average convex vacuum of formation, which can be represented in an equivalent form:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| (– – – +)  (+ – + –)  (+ + – –)  (+ – – –) + | (9.3) | ( – – + –)  ( + + – –)  ( + – – +)  ( + – – –) + | (9.4) | ( – + – –)  ( + – – +)  ( + – + –)  ( + – – –) + | (9.5) |

and three possibilities for the average concave vacuum formation:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| (+ + + –)  (– + – +)  (– – + +)  (– + + +) + | (9.6) | ( + + – +)  ( – – + +)  ( – + + –)  ( – + + +) + | (9.7) | ( + – + +)  ( – + + –)  ( – + – +)  ( – + + +) + | (9.8) |

Recall that the metrics (8.1) and (8.2) are special (limiting) cases of all other metrics (2.8) through (2.11) and (2.13) through (2.16) are solutions of the second vacuum equations (2.7). Therefore, the mathematical techniques outlined by the author, the Algebra of signatures as explained above, apply to all these derivations.

We will enter ideas of «quarks».

To do this, we write the ranks (9.3) through (9.8) as (9.9) through (9.11) as follows:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| *dr*+(+ + + –)  *ug*– (– + – +)  *ub*– (– – + +)  *р*1+(– + + +) + | (9.9) | *dg*+ (+ + – +)  *ub*– (– – + +)  *ur*–(– + + –)  *p*2+(– + + +) + | (9.10) | *db*+(+ – + +)  *ur*–(– + + –)  *ug*–(– + – +)  *p*3+(– + + +) + | (9.11) |

where *pi*+ are three different states of an «proton» (*i* = 1, 2, 3).

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| *dr*– (– – – +)  *ug*+ (+ – + –)  *ub*+ (+ + – –)  *р*1– (+ – – –) + | (9.12) | *dg*– ( – – + –)  *ub*+ ( + + – –)  *ur*+ ( + – – +)  *р*2– ( + – – –)+ | ( (9.13) | *db*– ( – + – –)  *ur*+ ( + – – +)  *ug*+ ( + – + –)  *р*3– ( + – – –)+ | (9.14) |

where *pi* are three different states of an «antiproton».

The sets of ten kinds of metrics (6.22) with the appropriate signatures from the matrix (8.12) will be termed as follows:

10 metrics [[4]](#footnote-4) of the form (6.22) with signature (+ + + –) : red *dr*+-«quark»;

10 metrics of the form (6.22) with signature (+ + – +) : green *dg*+-«quark»; (9.15)

10 metrics of the form (6.22) with signature (+ – + +) : blue *db*+-«quark»,

10 metrics of the form (6.22) with signature (– – – +) : red *dr*–-«antiquark»;

10 metrics of the form (6.22) with signature (– – + –) : green *dg*–-«antiquark»; (9.16)

10 metrics of the form (6.22) with signature (– + – –) : blue *db*–-«antiquark»,

10 metrics of the form (6.22) with signature (+ – – +) : red *ur*+-«quark»;

10 metrics of the form (6.22) with signature (+ – + –) : green *ug*+-«quark»; (9.17)

10 metrics of the form (6.22) with signature (+ + – –) : blue *ub*+-«quark».

10 metrics of the form (6.22) with signature (– + + –) : red *ur*–-«antiquark»;

10 metrics of the form (6.22) with signature (– + – +) : green *ug*–-«ntiquark»; (9.18)

10 metrics of the form (6.22) with signature (– – + +) : blue *ub*–-«antiquark».

In this case, the three «proton» states of and three «antiproton» states may be represented as

*p*1*+ = ug–ub–dr+, p*2*+ = ur– ub– dg+, p*3*+ =ug– ur– db+*, (9.19)

*p*1–*= ug–ub–dr+, p*2 *– = ur– ub– dg+, p*3*– =ug– ur– db+*, (9.20)

similar to the notation and composition of the proton and antiproton in the Standard Model and in quantum chromodynamics. However, within the framework of the Algebra of signatures, the «proton» and «antiproton» consist of «quarks» and «antiquarks», which allows us to outline ways to solve the problem of the coexistence of matter and antimatter. In addition, metric-dynamic models given by the Algebra of signatures are obtained in a more straightforward and informative way. For example, regard a multilayered metric-dynamic model of the «proton» in the state (9.9):

**«Рroton»** (9.21)

On the average, this is a concave multilayer vacuum formation

with a total (average) signature (9.9)

( + + +),

consisting of:

**[a] *dr*+-«quark»** (9.22)

with signature

(+ + + –)

**[a][i] Тhe outer shell of the *dr*+-«quark»**

in the interval [*r*5, *r*6]

(Figure 9.1):

,

,

,

,

**[a][ii] The сore of the** ***dr*+-«quark»** (9.23)

in the interval [*r*6, *r*7]

(Figure 9.1)

,

,

,

,

**[a][iii] The scope of the** ***dr*+-«quark»**  (9.24)

in the interval [0, ∞]



And

**[b] *ug*-«antiquark»**

with signature

( +  +)

which consists of:

**[b][i] The outer shell of the *ug*-«antiquark»**  (9.25)

in the interval [*r*5, *r*6]

(Figure 9.1)

,

,

,

,

**[b][ii] The core of** **the *ug*-«antiquark»** (9.26)

in the interval [*r*6, *r*7]

(Figure 9.1)

,

,

,



**[b][iii] The scope** **of** **the *ug*-«antiquark»** (9.27)

in the interval [0, ∞]

;

And

**[c] *ub*-«antiquark»** (9.28)

with signature

(– – + +)

**[c][i] The outer shell of the *ub*-«antiquark»**

in the interval [*r*5, *r*6]

(Figure 9.1):

,

,

,



**[c][ii] Тhe core of the *ub*-«antiquark»**  (9.29)

in the interval [*r*6, *r*7]

(Figure 9.1)

,

,

,

,

**[c][iii] The scope of the *ub*-«antiquark»** (9.30)

in the interval [0, ∞]:

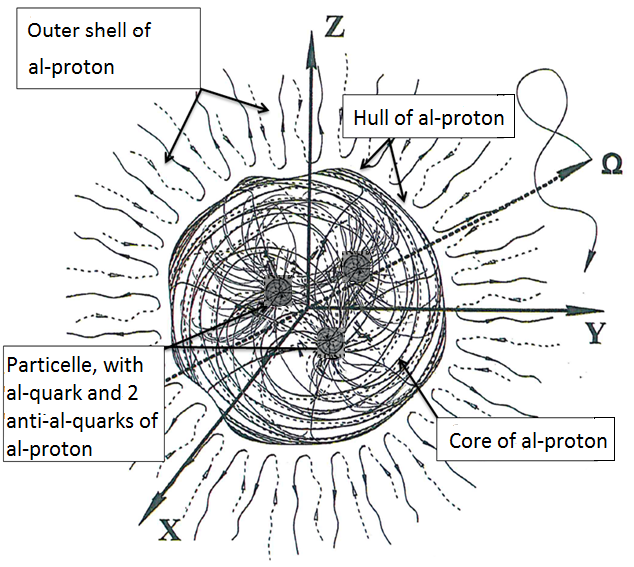
.



**Particelle, with «quark» and 2 «antiquark» of «proton»**

**Outer shell of «proton»**

**Fig. 9.1** An «proton» core essentially consists of the combination of a core with a valence *dr+*-«quark» and two valence *ug–* and *ub–*-«antiquarks». Three internal particelles of valence «quarks» are in constant random motion and intertwining with each other



**Abyss of «proton»**

**Core of «proton»**

When averaging in homogeneous terms of the metrics (9.22) through (9.30), we obtain a set of metrics (6.32), describing the metric-dynamic state which we have dubbed an «positron». However, it should be expected that the range of the «proton» core, consisting of three «quarks», is greater than the radius of the «positron» core, as the three «quarks» of the core repel one another away from their common center, where we set *r* = 0.

The problem of confinement of one «quark» and two «antiquarks» is immediately solved, because each «quark» or «antiquark» is an unstable "convex-concave" state of the vacuum extension. Only together, do they form a conditionally concave vacuum state with a stable average, thus forming an «proton» (Figure 9.1).

The average set of metrics (9.22) through (9.30) is a part of the solution of the simplified thirdEinstein field equation (6.21), as well as a set of metrics (6.32).

The «quarks» *ug–, ub–, dr+* are in chaotic motion with respect to the common center at *r* = 0 and relative to one other (Figure 9.1). On the average, they will thus make up an «proton»: <*rg*>= *r* = 0, <*rb*>= *r* = 0, <*rr*>= *r* = 0. Therefore, we have to use not only the metric-dynamic but also the statistical description of intranuclear processes; a fuller discussion of this may be found in (Batanov 2017).

The mathematical methods which have been briefly touched upon in Sections 1 to3 of this article, and developed more fully elsewhere (Gaukhman 2007/2008/2009/2017). These allow one to retrieve information on a variety of subtle processes and sub-processes that occur within the «proton» core, as in its outer shell, from the set of metrics (9.22) through (9.30)

**10.The «neutron»**

In modern nuclear physics, the neutron consists of two *d*-quarks with a charge of (1/3)*e* and a *u*-quark with a charge (2/3)*e* (where *е* – an electron charge)

*n = ddu*. (10.1)

As a result of this combination, a neutron is an electrically neutral particle with zero net charge (1/3) *e* + (1/3) *e* + (2/3) *e* = 0.

However, the desired result is achieved in the case of the rankings which we have outlined, consisting of four signatures. Therefore, the "electrically" neutral «particle» («neutron») may have the following topology (node) configuration:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| *iw*– (– – – –)  *db*+ (+ – + +)  *ur*– (– + + –)  *dg*+ (+ + – +)  *n*10 (0 0 0 0) + |  | *iw*– (– – – –)  *dg*+ (+ + – +)  *dr*+ (+ + + –)  *u*b– (– – + +)  *n*20 (0 0 0 0) + |  | *iw*– (– – – –)  *db*+ (+ – + +)  *ug*– (– + – +)  *dr*+ (+ + + –)  *n*30 (0 0 0 0) + | *iw*– (– – – –)  *ug*– (– + – +)  *db*+ (+ – + +)  *dr*+ (+ + + –)  *n*40 (0 0 0 0) + |

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| *iw*+ (+ + + +)  *db*– (– + – –)  *ur*+ (+ – – +)  *dg*– (– – + –)  *n*50 (0 0 0 0) + |  | *iw*+ (+ + + +)  *dg*– (– – + –)  *dr*– (– – – +)  *ub*+ (+ + – –)  *n*60 (0 0 0 0) + |  | *iw*+ (+ + + +)  *db*– (– + – –)  *ug*+ (+ – + –)  *dr*– (– – – +)  *n*70 (0 0 0 0) + | *iw*+ (+ + + +)  *ug*+ (+ – + –)  *db*– (– + – –)  *dr*– (– – – +)  *n*80 (0 0 0 0) + |

where

10 metrics are of the form (6.22) with signature (+ + + +) a white *iw*+-«quark»; (10.2)

10 metrics are of the form (6.22) with signature (   )a white *iw*-anti-2-quark. (10.3)

White «quarks» are so named because they are almost invisible within the core of the «neutron», since from the point of view of topology, they are a point of (8.13) and an anti-point of (8.14). Thus their presence in the «neutron» has not been observed experimentally, and thus do not make up part of the Standard Model.

Thus, under the methods of the Algebra of signatures, eight possible states of the «neutron» can be represented as:

*n*10 = *iw*–*db*+*dg*+*ur*–, *n*20 = *iw*–*dr*+*dg*+*ub*–, *n*30 = *iw*–*dr*+*db*+*ug*–, *n*40 = *iw*–*dr*+*db*+*ug*–,(10.4)

*n*50 = *iw*+*db*–*dg*–*ur*+, *n*60 = *iw*+*dg*–*dr*–*ub*+, *n*70 = *iw*+*db*–*dr*–*ug*+*, n*80 = *iw*+*db*–*dr*–*ug*+,

similar to the neutron in the Standard Model (10.1).

Due to the complicated "intracore" topological "metamorphosis", any additive four – «quark» combination (10.2) can be reconstructed so that the inside of the vacuum formation will consist of an «proton» and an «electron»:

|  |  |  |
| --- | --- | --- |
| (– – – –)  (+ – + +)  (– + + –)  (+ + – +)  (0 0 0 0) + | (+ – + +)  (– + + –)  (– + – +)  (+ – – –)  (0 0 0 0) + | «electron»  «proton» |

(10.5)

Apparently, this rebuilding ("unleashing") of a topological node inside the core, the «neutron», leads to the decomposition reaction

*n → p+ + e– + νe*, (10.6)

where *νe* is an «neutrino»[[5]](#footnote-5).

**11. The hydrogen «atom»**

Compared with the «neutron», a substantially more stable neutral vacuum formation is the core of the «atom» of hydrogen.

According to astronomical observations, visible matter in the Universe consists of approximately three quarters hydrogen and approximately a quarter helium, with the other chemical elements accounting for only around two percent.

A neutral atom of deuterium is composed of one proton, one neutron and one electron. As part of the Algebra of signatures, it turns out that the «atom» of deuterium is composed of an «proton», an neutron and an «electron». The rank (topological) equivalent nodal configuration of such a region of the vacuum is as follows:

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| «proton»  +  «neutron»  +  «electron»  = | (+ + + –)  (– + – +)  (– – + +)  (– – – –)  (+ – + +)  (– + + –)  (+ + – +)  (+ – – –)  1Н(0 0 0 0)+ | or | (+ + – +)  (– – + +)  (– + + –)  (+ + + +)  (+ – + –) or …  (– + – –)  (– – – +)  (+ – – –)  1Н(0 0 0 0) + | (11.1) |

Such combinations can create a set that reflects the possibility of "color" combinatorics of intracore metamorphosis. But the topological configuration of the "unit" always remains the same: three *u*-«quarks», three *d*-«quarks», one *i*-«quark» and one *e*-«quark» («electron»). We denote this topological "node" in the following way:

1*Н* = 3*u*3*die*,(11.2)

Taking into account the topological properties of the metric with the appropriate signatures (8.13) through (8.16), we find that the "node" consists of three twisted "torahs", four oval surfaces and a "point".

Similarly, all the known chemical elements of the Mendeleev’s periodic table could be constructed, or following up on our previous image, braided, whereby the average size of their nuclei *rn* would depend on the number of «quarks» *A* forming the "topology nodes": *rn* ≈½*А*1/3*r6* ≈ ½ *А*1/3·10-13cm.

It is tempting to postulate that these discrete radii in stable vacuum states form a Fibonacci or other Lucas sequence. To follow up on this idea, a task which we shall not attempt here, an appropriate starting point would be to apply equation (7.8) with *rk* = *r*6.

**12. «Fermions» in the Algebra of signatures**

Having a set out of 16 colored «quarks» (9.15) through (9.18) and (10.3) (as summarized in Table 12.1) and understanding their topological features, all fermions (mesons and baryons) from the Standard Model can be braided.

Table 12.1

|  |  |  |  |
| --- | --- | --- | --- |
| «Quarks» | | «Antiquarks» | |
| 10 metrics  type (6.22)  or (12.1)  with signature: | «quark» | 10 metrics  type (6.22)  or (12.1)  with signature: | «antiquark» |
| (+ – – –) | *e*+**-**«quark», or «electron» | (– + + +) | *e*–*-*«antiquark»,  or «positron» |
| (+ + + –)    (+ + – +)    (+ – + +) | *d*r+*-*«quark»  *d*g+**-**«quark»  *d*b+**-**«quark» | (– – – +)    (– – + –)    (– + – –) | *d*r–*-*«antiquark»    *d*g–**-«**antiquark»  *d*b–**-«**antiquark» |
| (+ – – +)    (+ – + –)  (+ + – –) | *ur*+**-**«quark»  *ug*+**-«**quark»  *ub*+**-**«quark» | (– + + –)  (– + – +)    (– – + +) | *ur*–**-«**antiquark»  *ug*–**-«**antiquark»  *ub*–**-«**antiquark» |
| (+ + + +) | *iw*+**-**«quark»  (“invisibles”) | (– – – –) | *iw*–**-«**antiquark»  (“anti-invisibles”) |

where, for example,

***uk*-«antiquark»**  (12.1)

with signature is

( + + )

composed of:

**The outer shell of the *uk*-«antiquark»** (12.2)

in the interval [*r*5, *r*6]

(Figure 9.1)

,

,

,

,

**The core of the *uk*-«antiquark»** (12.3)

in the interval [*r*6, *r*7]

(Figure 9.1)

,

,

,

,

**The scope of the *uk*-«antiquark»** (12.4)

in the interval [0, ∞]

.

In quantum chromodynamics, mesons are composed of a quark and an antiquark, and are given by

, (12.5)

where *qα*+ (*α = b, g, r*) is a quark (or antiquark) color tripletand *qα–* is an antiquark color triplet.

Baryons composed of 3 quarks, and are given by

**, (12.6)

where *ε*αβγ are completely antisymmetric tensor.

«Mesons» and «baryons» are formed in the same way in the Algebra of signatures. Consider a specific example: three types of pi-mesons subject to strong interactions have the quark structure:

 (12.7)

In the Algebra of signatures, such as the meson *π+ = u– d +* is represented as

|  |  |  |
| --- | --- | --- |
| *dr+* (+ + + –)  *ug–* (– + – +)  *π*1+ (0 2+ 0 0) *+* | *dg+* (+ + – +)  *ub–* (– – + +)  *π*2+ (0 0 0 2+)*+* | *db+*( + – + +)  *ur–* ( – + + –)  *π3+*(0 0 2+ 0) *+* |

(12.8)

for which each signature corresponds to the set of ten metrics of the type (12.1).

Even from within these ranks it is seen that such a convex-concave vacuum formation cannot be stable. They can arise from this topological configuration, but in this way, they instantly disappear, blur together or collapse to nodes resulting from the intertwining of the inside vacuum currents in the curved region of the vacuum.

In turn, the «quark» structure

 (12.9)

can have the following signature (topological) analogues:

|  |  |  |
| --- | --- | --- |
| *u* r*+* (+ – – +)  *u*g*–* (– + – +)*+*  –  *d* r*+* (+ + + –)  *d*g*–* (– –­ + –)*+*  *π*10 (0 0 0 0) | *u*g*+* (+ – + –)  *u*b*–* (– – + +)*+*  –  *d*g*+* (+ + – +)  *d*b*–* (– + –­ –)*+*  *π*20 (0 0 0 0) | *u*b*+* (+ + – –)  *u* r*–* (– + + –)*+*  –  *d*b*+* (+ – + +)  *d* r*–* (–­ – – +)*+*  *π*30 (0 0 0 0) |

(12.10)

Similarly, under the Algebra of the signature all known mesons and baryons from the Standard Model can be braided.

The Algebra of signatures differs from the Standard Model only in the presence of its other "invisible": *ib*+-«quark» and *ib*-«antiquark».

**13. «Bosons» in the Algebra of signatures**

The local part of the flat outer side of the vacuum region is described by the metric (8.1)

*ds*(–)2 = *с*2*dt*2 – *dx*2 – *dy*2 – *dz*2 = *ηij*(–)*dxidxj* with the signature (+ – – –), (13.1)

where

, (13.2)

and the same lengths of the inside of the vacuum region is described by the metric (8.2)

*ds*(+)2 = –*с*2*dt*2 + *dx*2 + *dy*2 + *dz*2 = *ηij*(+)*dxidxj* with signature (– + + +)

where

. (13.3)

As part of the Algebra of signatures, weak perturbations of a two-way vacuum over a given 2-braid (averaged metric) take the form

½(*ds*(–)2 + *ds* (+)2) *=* ½(*ηij*(–) + *hij*(–) + *ηij*(+) – *hij*(+)) *dxidxj* = ½(*hij*(–) – *hij*(+)) *dxidxj,*(13.4)

where *hij*() and *hij*(+) are related components of the tensors defining slight bilateral deviations from the state of the original uncurved vacuum region.

We assume a fixed reference system in a fashion similar to the fixing of the electromagnetic vector potential in the Lorentz gauge condition in electrodynamics (Landau and Lifshitz 1988). We further impose additional conditions on *hij*(–) and *hij*(+), so that the first vacuum Einstein equation (1.6) is reduced to the wave equation

 (13.5)

In a small area of ​​the vacuum, the wave disturbance can be regarded as a plane wave. If the direction of wave propagation is represented along the *x*-axis, a suitable choice of the reference system will make the components *hij*() and *hij*(+) vanish, as well as the components

*h*22(–) =– *h*33(–) ≡ *h*+(–) and *h*32 (–) = *h*23(–) ≡ *h*×(–).(13.6)

*h*22(+) =– *h*33(+) ≡ *h*+(+) and *h*32 (+) = *h*23(+) ≡ *h*×(+).

Such a wave disturbance is a quadrupolar transverse wave. The polarization of this wave in the *u-z* plane is defined by the following tensor of the second rank:

  *a*, *b =* 2, 3. (13.7)

The separate components, *h*+(–) and *h*×(–), *h*+(+) and *h*×(+),describe two independent polarization planes of the quadrupolar wave disturbances which differ from each other by a rotation through an angle of *π*/4.

The average second-rank tensor

 (13.8)

can describe, under certain phase relationships, not only the quadrupolar but also the dipolar, including linear, elliptical and circular polarization wave disturbances of a two-sided extension.

Thus, the first Einstein field equation (1.6) is linearized for small perturbations of the metric, i.e., it becomes the wave (13.5), and allows the distribution of different types of wave disturbances on the two-sided vacuum region.

The problem of propagation of wave disturbances throughout the vacuum can be considered in a different way. We start with the metric (13.1)

*ds*(–)2 *= с*2*dt*2 – *dx*2 – *dy*2 – *dz*2= 0 with the signature (+ – – –). (13.9)

This determines not only the metric-dynamic properties of the flat outer side of the vacuum region, but also the spread of the light beam in a vacuum at a forward speed of *сdt* = (*dx*2 + *dy*2 + *dz*2)1/2.

In this metric (13.3)

*ds*(+)2= – *с*2*dt*2 + *dx*2 + *dy*2 + *dz*2 = 0 with signature (– + + +). (13.10)

determines not only the metric-dynamic properties of the flat inner side of the vacuum region, but also the spread of the light beam in a vacuum at a speed from the opposite direction  *сdt* =(*dx*2+*dy*2+*dz*2)1/2.

Recall that the quadratic form (15.9) and (15.10) can be represented as a product of linear (affine) forms (1.37) and (1.38)

*ds*(–)2 *= с*2*dt*2 – *dx*2 – *dy*2 – *dz*2= *сdt*′*сdt*′′– *dx*′*dx*′′– *dy*′*dy*′′– *dz*′*dz*′′, (13.11)

*ds*(+)2= – *с*2*dt*2 + *dx*2 + *dy*2 + *dz*2 = – *сdt*′*сdt*′′+*dx*′*dx*′′+*dy*′*dy*′′+*dz*′*dz*′′, (13.12)

where, according to (1.39) through (1.42):

*ds*(–)′ = *сdt*′– *dx*′– *dy*′– *dz*′  "Cover" of the outer side of the vacuum; (13.13)

*ds*(–)′′ = *сdt*′′– *dx*′′– *dy*′′– *dz*′′  "Inside" of the outer side of the vacuum; (13.14)

*ds*(+)′ = – *сdt*′+ *dx*′+ *dy*′+ *dz*′  "Cover" of the inner side of the vacuum; (13.15)

*ds*(+)′′ = – *сdt*′′+ *dx*′′+ *dy*′′+ *dz*′′  "Inside" of the inner side of the vacuum. (13.16)

Since the segments from (13.13) through (13.16) are perpendicular to each other:

*ds*(–)′⊥ *ds*(–)′′⊥ *ds*(+) ′⊥ *ds*(+)′′,

the language of quaternions is the most effective form to handle them.

In that case, instead of the linear form (13.13), we use quaternion

*z* = – *x*0 + *ix*1 + *jx*2+ *kx*3 ,*stignature* { + + +} (13.17)

and instead of (13.15) , the complex conjugate quaternion

*z*\* = *x*0 *–xi*3 *– jx*2 *– kx*1 , *stignature* {+ – – –} (13.18)

In general, the Algebra of signatures admits the existence of 16 types of "color" quaternions with all possible stignatures:

|  |  |
| --- | --- |
| *z*1 = *x*0 + *ix*1 + *jx*2+*kx*3 {+ + + +}  *z*2 = –*x*0 – *ix*1 – *jx*2+ *kx*3 {– – – +}  *z*3 = *x*0 –*ix*1 – *jx*2+ *kx*3 {+ – – +}  *z*4 = –*x*0 – *ix*1+ *jx*2– *kx*3 {– – + –}  *z*5 = *x*0 +*ix*1 – *jx*2 – *kx*3 {+ + – –}  *z*6 = –*x*0 + *ix*1 – *jx*2– *kx*3 {– + – –}  *z*7 = *x*0 – *ix*1 + *jx*2– *kx*3 {+ – + –}  *z*8 = –*x*0 + *ix*1 + *jx*2+*kx*3 {– + + +} | {– – – –} *z*9 = –*x*0 –*ix*1 – *jx*2–*kx*3  {+ + + –} *z*10 = *x*0 + *ix*1 + *jx*2– *kx*3  {– + + –} *z*11= –*x*0 +*ix*1 + *jx*2 – *kx*3  {+ + – +} *z*12= *x*0 + *ix*1 – *jx*2 + *kx*3  {– – + +} *z*13= –*x*0 – *ix*1 + *jx*2+ *kx*3  {+ – + +} *z*14= *x*0 –*ix*1 + *jx*2+ *kx*3  {– + – +} *z*15 = –*x*0 + *ix*1– *jx*2+ *kx*3  {+ – – –} *z*16 = *x*0 – *ix*1 – *jx*2– *kx*3 |

(13.19)

By a straightforward calculation, it is easy to see that the sum of all 16 types of "color" quaternions (13.19) is equal to zero

*z*1 + *z*2 + *z*3 + *z*4 + *z*5 + *z*6 + *z*7 + *z*8 + *z*9 + *z*10 + *z*11 + *z*12 + *z*13 + *z*14 + *z*15 + *z*16 = 0, (13.20)

so that we can consider that the vacuum itself satisfies the condition.

Equivalent stignatures from (13.20) take on the form:

{+ + + +} + {– – – +} + {+ – – +} + {+ + – –}+

+ {+ – + –} + {– + – –} + {+ – + –} + {– + + +} + (13.21)

+ {– – – –} + {+ + + –} + {– + + –} + {+ + – +} +

+ {– – + +} + {+ – + +} + {– + – +} + {+ – – –}= {0000}.

stignatures form a structure similar to the signature structure and antisymmetric matrix referred to earlier in this paper

 (13.22)

A more detailed analysis of the 16 aggregate stignatures and the "colored" quaternions is given in (Gaukhman 2007).

**13.1. The «photon» and «antiphoton»**

Because, for example, the linear forms (13.13) and (13.14) are mutually perpendicular in relation to the other arcs, the harmonic disturbance, extending on the total extent of the metric (i.e., the outside of the vacuum) can be written as:

cos{(2*π/λ*)(*сt–x–y–z*)} *+ i* sin{(2*π/λ*)(*сt–x–y–z*)} =ехр {*i* (2*π/λ*)(*сt–x–y–z*)}*=* ехр {*i*(*ω t –* **k***⋅* **r**)}.

(13.23)

We call such a harmonic disturbance of the metric an «photon» having a metric with stignature {+   }.

Similarly, for mutually perpendicular linear forms (13.15) and (13.16) we have the harmonic disturbance inside the vacuum region:

cos{(2*π /λ*)(*–сt+x+y+z*)} *+ i* sin{(2*π/λ*)(*–сt+x+y+z*)} =ехр {*i* (2*π/λ*)(*–сt+x+y+z*)}*=* ехр *–*{*i*(*ω t –* **k***⋅* **r**)}.

(13.24)

which we call «antiphoton» with stignature { + + +} because it extends in the opposite direction with respect to the «photon». (This is not to be confused with the antimatter particle of the photon, which is of course the photon itself).

**13.2. The W±-«bosons»**

Similar constructions show that six signature ranks: (13.25)

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| {– – – +}  {+ – + –}  {+ + – –}  {+ – – –}+ |  | {– – + –}  {+ + – –}  {+ – – +}  {+ – – –}+ |  | { – + – –}  { + – – +}  { + – + –}  {+ – – –}+ |  |

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| {+ + + –}  {– + – +}  {– – + +}  {– + + +}+ |  | {+ + – +}  {– – + +}  {– + + –}  {– + + +}+ |  | {+ – + +}  {– + + –}  {– + – +}  {– + + +}+ |  |

correspond to three colored states of the W-«boson»

|  |  |
| --- | --- |
| ехр {*i*2*π /λ* (– *сt* – *x* – *y* + *z*)}×  × ехр {*j*2*π /λ* ( *сt* – *x* + *y* – *z*)}×  × ехр {*k* 2*π /λ* ( *сt* + *x* – *y*– *z*)} | {– – – +}  {+ – + –}  {+ + – –}  {+ – – –}+ |
| ехр {*i*2*π /λ* (– *сt* – *x* + *y* – *z*)}×  × ехр {*j*2*π /λ* ( *сt* + *x* – *y* – *z*)}×  × ехр {*k* 2*π /λ* ( *сt* – *x* – *y*+ *z*)} | {– – + –}  {+ + – –} (13.26)  {+ – – +}  {+ – – –}+ |
| ехр {*i*2*π /λ* (– *сt* + *x* – *y* – *z*)}×  × ехр {*j*2*π /λ* ( *сt* – *x* – *y* + *z*)}×  × ехр {*k* 2*π /λ* ( *сt* – *x* + y– *z*)} | {– + – –}  {+ – – +}  {+ – + –}  {+ – – –}+ |

and three colored states of the W-«boson»

|  |  |
| --- | --- |
| ехр {*i*2*π /λ* ( *сt* + *x* + *y* – *z*)}×  × ехр {*j*2*π /λ* (– *сt* + *x* – *y* + *z*)}×  × ехр {*k* 2*π /λ* (– *сt* – *x* + *y*+ *z*)} | {+ + + –}  {– + – +}  {– – + +}  {– + + +}+ |
| ехр {*i*2*π /λ* ( *сt* + *x* – *y* + *z*)}×  × ехр {*j*2*π /λ* (– *сt* – *x* + *y* + *z*)}×  × ехр {*k* 2*π /λ* (– *сt* + *x* + *y*–*z*)} | {+ + – +}  {– – + +} (13.27)  {– + + –}  {– + + +}+ |

|  |  |
| --- | --- |
| ехр {*i*2*π /λ* ( *сt* – *x* + *y* + *z*)}×  × ехр {*j*2*π /λ* (– *сt* + *x* + *y* – *z*)}×  × ехр {*k* 2*π /λ* (– *сt* + *x* – *y*+ *z*)} | {+ – + +}  {– + + –}  {– + – +}  {– + + +}+ , |

where *i*, *j*, *k* are the imaginary units forming an anticommutative algebra:

*i* 2*= j* 2*= k* 2 = *ijk =* *–*1 and *ij + ji =* 0. (13.28)

**13.3. The Z0-«bosons»**

The six signature ranks

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| {– – – –}  {+ – + +}  {– + + –}  {+ + – +}  {0 0 0 0}+ |  | {– – – –}  {+ + – +}  {+ + + –}  {– – + +}  {0 0 0 0}+ |  | {– – – –}  {+ – + +}  {– + – +}  {+ + + –}  {0 0 0 0}+ |  |

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| {+ + + +}  {– + – –}  {+ – – +}  {– – + –}  {0 0 0 0)+ |  | {+ + + +}  {– – + –}  {– – – +}  {+ + – –}  {0 0 0 0}+ |  | {+ + + +}  {– + – –}  {+ – + –}  {– – – +}  {0 0 0 0}+ |  |

(13.29)

correspond to the six color states of the *Z*0-«boson»

|  |  |  |
| --- | --- | --- |
| ехр { 2*π /λ* (– *сt* – *x* – *y* – *z*)}×  × ехр {*i*2*π /λ* ( *сt* – *x* + *y* + *z*)}×  × ехр {*j* 2*π /λ* (– *сt* + *x* + *y*– *z*)}×  × ехр {*k*2*π /λ* ( *сt* + *x* – *y* + *z*)} | {– – – –}  {+ – + +}  {– + + –}  {+ + – +}  {0 0 0 0}+ | |
| ехр { 2*π /λ* (– *сt* – *x* – *y* – *z*)}×  × ехр {*i*2*π /λ* ( *сt* + *x* – *y* + *z*)}×  × ехр {*j* 2*π /λ* ( *сt* + *x* + *y*– *z*)}×  × ехр {*k*2*π /λ* (– *сt* – *x* + *y* + *z*)} | {– – – –}  {+ + – +}  {+ + + –}  {– – + +}  {0 0 0 0}+ | |
| ехр { 2*π /λ* (– *сt* – *x* – *y* – *z*)}×  × ехр {*i*2*π /λ* ( *сt* – *x* + *y* + *z*)}×  × ехр {*j* 2*π /λ* (– *сt* + *x* – *y*+ *z*)}×  × ехр {*k*2*π /λ* ( *сt* + *x* + *y* – *z*)} | {– – – –}  {+ – + +}  {– + – +}  {+ + + –}  {0 0 0 0}+ | |
| ехр { 2*π /λ* ( *сt* + *x* + *y* + *z*)}×  × ехр {*i*2*π /λ* (– *сt* + *x* – *y* – *z*)}×  × ехр {*j* 2*π /λ* ( *сt* – *x* – *y*+ *z*)}×  × ехр {*k*2*π /λ* (– *сt* – *x* + *y* – *z*)} | {+ + + +}  {– + – –}  {+ – – +}  {– – + –}  {0 0 0 0}+ | |
| ехр { 2*π /λ* ( *сt* + *x* + *y* + *z*)}×  × ехр {*i*2*π /λ* (– *сt* – *x* + *y* – *z*)}×  × ехр {*j* 2*π /λ* (– *сt* – *x* – *y*+ *z*)}×  × ехр {*k*2*π /λ* ( *сt* + *x* – *y* – *z*)} | {+ + + +}  {– – + –}  {– – – +}  {+ + – –}  {0 0 0 0}+ |

|  |  |
| --- | --- |
| ехр { 2*π /λ* ( *сt* + *x* + *y* + *z*)}×  × ехр {*i*2*π /λ* (– *сt* + *x* – *y* – *z*)}×  × ехр {*j* 2*π /λ* ( *сt* – *x* + *y*– *z*)}×  × ехр {*k*2*π /λ* (– *сt* – *x* – *y* + *z*)} | {+ + + +}  {– + – –}  {+ – + –}  {– – – +}  {0 0 0 0}+ |

(13.30)

**13.4. The «graviton»**

In the Algebra of signatures, another «boson» appears, namely, the «graviton».

|  |  |
| --- | --- |
| ехр {*ζ*12*π /λ* ( *сt* + *x* + *y* + *z*)}  × ехр {*ζ*32*π /λ* ( *сt* – *x* – *y*+ *z*)}×  × ехр {*ζ*42*π /λ* (–*сt*– *x* + *y* – *z*)}×  × ехр {*ζ*5 2*π /λ* ( *сt*+ *x* – *y* – *z*)}×  × ехр{*ζ*62*π /λ* (– *сt* + *x* – *y* – *z*)}×  × ехр {*ζ*72*π /λ* ( *сt* – *x* + *y* – *z*)}×  × ехр {*ζ*82*π /λ* (– *сt+* *x* + *y* +*z*)}×  × ехр {*ζ*1 2*π /λ* (– *сt* –*x* – *y* – *z*)}×  × ехр{*ζ*22*π /λ* ( *сt* + *x* + *y* – *z*)}×  × ехр{*ζ*32*π /λ* (– *сt* + *x* + *y*– *z*)}×  × ехр{*ζ*42*π /λ* ( *сt* + *x* – *y* + *z*)}×  × ехр (*ζ*5 2*π /λ* (– *сt*– *x*+ *y* + *z*)}×  × ехр{*ζ*6 2*π /λ* ( *сt* – *x* + *y* + *z*)}×  × ехр {*ζ*72*π /λ* (– *сt* + *x*– *y* + *z*)}×  × ехр {*ζ*82*π /λ* ( *сt* – *x* – *y* – *z*)} | {+ + + +}  {– – – +}  {+ – – +}  {– – + –}  {+ + – –}  {– + – –}  {+ – + –}  {– + + + }  {– – – – }  {+ + + – }  {– + + – }  {+ + – +}  {– – + +}  {+ – + +}  {– + – +}  {+ – – –}  {0 0 0 0}+ |

(13.31)

whereby the *ζm* entities satisfy the anticommutative relations of a Clifford algebra.

*ζm ζk*+ *ζk**ζm* = 0 for *m* ≠ *k* , *ζm* *ζm* = 1, or *ζm ζk* + *ζk**ζm* = 2*δkm*,(13.32)

where *δkm* is the Kronecker delta (*δkm* = 0 for *m* ≠ *k* and *δkm* = 1 for *m* = *k*). One way to define objects and *ζm* entities and the Kronecker delta *δkm* is presented below:









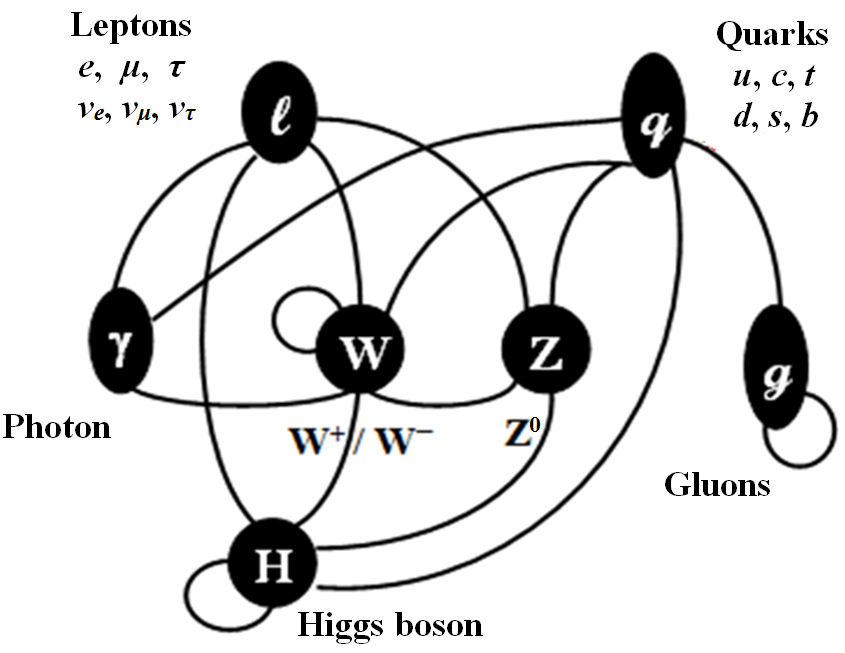
 (13.33)

**14. Conclusion**

In this paper, supported by a 16-sheeted atlas of metric spaces with sixteen types of signatures (topologies) (8.12) and a 32-page set of affine subspaces with stignatures (13.21), we obtain the metric-dynamic models of virtually all elements of the Standard Model.

Not considered in this article were the analogues of neutrinos, muons, tau-leptons and Higgs bosons. Metric - dynamic models of vacuum entity data (except for the Higgs boson), and the interaction between the spherical vacuum formations («particles») are shown by Gaukhman (Gaukhman 2008).

**Fig 14.1** Components of the Standard Model



The massless geometrophysics proposed here is completely missing the concept of mass, so there is no need to introduce fields beyond those implicit in the field equations. This mechanism allows for spontaneous electroweak symmetry breaking, and accordingly the quantum of this field is the Higgs boson.

A geometrized description of all force interactions (gravitational, electromagnetic, electroweak, nuclear and torsion) is partly given in (Gaukhman 2008/2009/2017) and will be elaborated in the next article in English by the author.

Mathematical techniques to extract a variety of information about the local entities of the plurality of Einstein field equations solutions are shown in an article by Gaukhman (Gaukhman 2007/2017).

An article by Krivonosov & Lukyanov (2009) shows that the Yang -Mills equations in four-dimensional space with conformal connection torsion reduce to Einstein's equations, Maxwell's equations, and another group of 10 of second-order differential equations. Another article by the same authors (Krivonosov & Lukyanov, 2011) provides a general solution to these equations for a centrally symmetric metric in the absence of an electromagnetic field, and also shows that among particular solutions of these equations, expressed in terms of elementary functions, there is a solution which is a Kottler metric.

In this article Kottler solutions are at the heart of model representations of the metric-dynamic vacuum organization as a whole given in (5.4) through (5.13), including the local spherical vacuum formations such as (6.22), (6.32) and (12.1). Therefore, the framework of the Algebra of signatures provides a complete metric-dynamic «quark» model (Table 12.1) and practically all analogues of fermions and bosons (section 13.1 through 13.4) included in the Standard Model are also included in this framework, in line with the conclusions of (Krivonosov & Lukyanov 2009/2011). These may then be proposed as a set of analytical solutions of the Yang-Mills theory.

Note that, if a set of metrics form (6.22) (6.32) and (12.1), then instead of:

*r*5 ~ 4,9·103 cm: ~ «biological cage» inner core;

*r*6 ~1,7·1013 cm: ~ core of an elementary «particle»;

*r*7 ~ 5,8·1024 cm: ~ core of an «protoquark»;

we could substitute, for example,

*r*2 ~ 1,2·1029 cm: ~ «metagalaxy» inner core;

*r*3 ~ 4·1018 cm: ~ «galaxy» inner core;

*r*4 ~ 1,4·108 cm: ~ «star» or «planet» inner core,

continuing in an analogous manner, we obtain a geometrophysics and a topological description of the extent of the vacuum also on astronomical scales.

It appears to the author that this results in a universal metric-dynamic model of the closed universe which is, at the same time, on the average Ricci-flat; this universe is then populated by an infinite number of spherical vacuum formations of various sizes.

The usual probabilistic formalism of the Standard Model is still valid, as the core and “particelles” are stable vacuum formations constantly and randomly moving under the influence of the neighboring stable vacuum formations and a variety of other vacuum fluctuations. Study of chaotic motion of the vacuum nucleation has led to an alternate derivation of the Schrödinger equation (Batanov 2017), and (Gaukhman 2008) shows the relationship of the Algebra of signatures to quantum theory.

The Algebra of signatures proposed in this article is not an alternative theory opposed to general relativity, quantum field theory and superstring theory, but rather their symbiosis via a full geometrization of physical laws.

**Acknowledgements**

My sincere thanks to David Reid for assisting in the editing and creative translation of this article into English. I am also grateful to S.V. Przhigodsky and to Dr. V.A. Lukyanov for their valuable remarks which have undoubtedly led to an improvement in the quality of this paper.

Terms of the Algebra of signatures were adapted (from the Russian original) for the English version of this article by the translator, David Reid.

**Bibliography**

[1] Batanov, M.B. (2017, 7 Feb.) Derivation of the Schrödinger equation.

https://arxiv.org/abs/1702.01880 [physics.gen-ph].

[2] De Sitter, W. (1979), "O teorii tyagoteniya Eynshteyna i yeye sledstviyakh dlya astronomii”. Stat'ya III (On Einstein‘s theory of gravity and its consequences for astronomy. Article III) in Al’bert Eynshteyn i teoriya gravitatsii (Albert Einstein and the theory of gravity) – Moscow, Russia. Mir Publishing House [In Russian].

[3] Einstein, A. (1928) Riemann-Geometrie mit Aufrechterhaltung des Begriffes des Fernparallelismus (Riemann Geometry maintaining the concept of Fernparallellismus). Sitzungsbericht der preussischen Akadamie der Wissenschaften. (Minutes of the Prussian Academy of Sciences) – Berlin, Germany. Verlag der Königlich-Preussischen Akademie der Wissenschaften p. 217-221 [In German].

[4] Einstein, A. (1966) Sobraniye nauchnykh trudy. t. 2 (Collection of scientific works. Vol.2) – Moscow, Russia. Nauka [In Russian].

[5] Einstein, A. (1967) Avtobiograficheskiye zametki. Sobraniye nauchnykh trudov. t. 4 (Autobiographical notes. Collection of scientific works. Vol.4) – Moscow, Russia. Nauka, pp. 259-294 [In Russian].

[6] Gaukhman, M. Kh. (2004) Algebra signatur (Krasnaya Alsigna) [Algebra of signatures (Red Alsigna).] – Moscow, Russia (available in www.alsignat.narod.ru.) [In Russian].

[7] Gaukhman, M. Kh. (2007) Pustota (Zheltaya Alsigna) [Void (Yellow Alsigna)]. In Algebra signatur [Algebra of signatures] – Moscow, Russia (available in www.alsignat.narod.ru.) [In Russian].

[8] Gaukhman, M.Kh. (2008) Chastitsy (Zelenaya Alsigna) [Particles (Green Alsigna)]. In Algebra signatur [Algebra of signatures] – Moscow, Russia: Librokom (available in www.alsignat.narod.ru.) [In Russian].

[9] Gaukhman, M.Kh. (2009) Gravitatsiya (Golubaya Alsigna) [Gravity (Light blue Alsigna). In Algebra signatur [Algebra of signatures] – Moscow, Russia: Librokom (available in [www.alsignat](http://www.alsignat). narod.ru.) [In Russian].

[10] Gaukhman, M.Kh. (2015) Kosmogenezis (Sinyaya Alsigna) [Cosmogenesis (Blue Alsigna). In Algebra signatur [Algebra of signatures] – Moscow, Russia: MIG (Media Info Group) (available in www.alsignat.narod.ru.) [In Russian].

[11] Gaukhman, M.Kh. (2017) Bezmassovaya fizika (Fioletovaya Alsigna) [Massless physics (Violet Alsigna). In Algebra signatur [Algebra of signatures] – Moscow, Russia: Filin Publishing House (available in www.alsignat.narod.ru.) [In Russian].

[12] Hobson, A. (2012, 29 Nov.) There are no particles, there are only fields. Am. J. Phys. 81 (3), March 2013, 211-223. arXiv:1204.4616v2.

[13] Ivanenko, D.D., Pronin, P.I. & Sardanashvili, G.A. (1985) Kalibrovochnaya teoriya gravitatsii (Gauge gravitation theory) – Moscow, Russia. Publishing house of Moscow State University.

[14] Klein, F. (2004) Neyevklidova geometriya (Non-Euclidean geometry) – Moscow, Russia. Editorial URSS [In Russian].

[15] Krivonosov, L.N. & Lukyanov, V.A. (2009) Svyaz' uravneniy Yanga-Millsa s uravneniyami Eynshteyna i Maksvella (Connection of the Yang-Mills equations with the Einstein and Maxwell equations) - Krasnoyarsk, Russia: Zhurnal Sibirskogo federal'nogo universiteta., Seriya Matematika i fizika 2: 4 (Journal of the Siberian Federal University. Series Mathematics and Physics, 2: 4), pp. 432-448 [In Russian].

[16] Krivonosov, L.N. & Lukyanov, V.A. (2011), Polnoye resheniye uravneniy Yanga-Millsa dlya tsentral'no-simmetricheskoy metriki (A complete solution of the Yang-Mills equations for a centrally symmetric metric) - Krasnoyarsk, Russia. Zhurnal Sibirskogo federal'nogo universiteta (Journal of the Siberian Federal University) [In Russian].

[17] Landau, L.D. & Lifshits, E.M. (1988) Teoriya polya. Tom 2 (Field Theory. Volume 2) – Moscow, Russia. Nauka [In Russian].

[18] Novikov, S.P. & Taimanov, I.A. (2014) Sovremennyye geometricheskiye struktury i polya (Modern geometric structures and fields) – Moscow, Russia. Moscow Center for Continued Education in Mathematics [In Russian].

[19] Riemann, B. Fragmenty filosofskogo soderzhaniya. Al'bert Eynshteyn i teoriya gravitatsii (Fragments of philosophical content. Albert Einstein and the theory of gravitation) – Moscow, Russia. Mir Publishing House. pp. 34-35 [In Russian].

[20] Sedov, L.I. (1994) Mekhanika sploshnykh sred. t.1 (Mechanics of continuous media. Vol. 1) –

Moscow, Russia. Nauka, 1994 [In Russian].

[21] Shipov, G.I. (1997) Teoriya fizicheskogo vakuuma (Theory of physical vacuum.) – Moscow, Russia. Nauka [In Russian].

[22] Vladimirov, Yu.V. (2005) Geometrofizika (Geometrophysics) – Moscow, Russia. Binom [In Russian].

1. [alsignat@yandex.ru](mailto:alsignat@yandex.ru) [↑](#footnote-ref-1)
2. The concept of the geometrophysics is entered in (Vladimirov 2005) [↑](#footnote-ref-2)
3. Realized for *r*0=2 using MathCad 14 [↑](#footnote-ref-3)
4. 10 metrics are of the form (6.22), because the scope (6.31), as well as the core, are related to the outer shell. In this way, 5 metrics describe the core, and 5 metrics describe the outer shell, to make up the total of 10 metrics. [↑](#footnote-ref-4)
5. Metric-dynamic models of various grades «neutrino» are considered in (Gaukhman 2008). [↑](#footnote-ref-5)